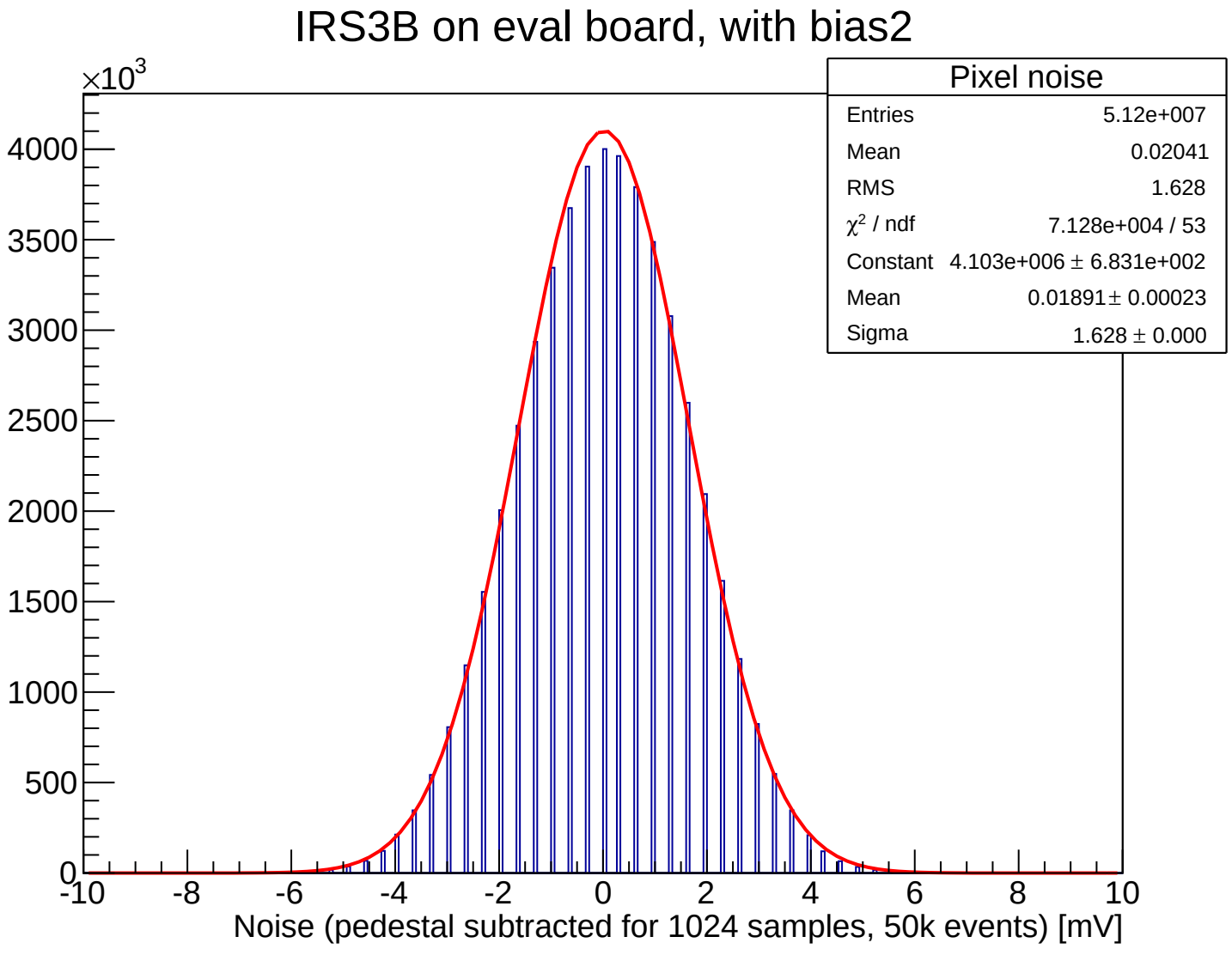
IRS3B on eval board, with bias2
Pixel noise
Entries 5.12e+007
Mean 0.02041
RMS 1.628
χ2 / ndf 7.128e+004 / 53
Constant 4.103e+006 ± 6.831e+002
Mean 0.01891 ± 0.00023
Sigma 1.628 ± 0.000
×10^3
4000
3500
3000
2500
2000
1500
1000
500
0
-10
-8
-6
-4
-2
0
2
4
6
8
10
Noise (pedestal subtracted for 1024 samples, 50k events) [mV]