

bPID Beam Test Electronics – Integration Status and Plans

Matt Andrew, Kurtis Nishimura, Gary Varner

University of Hawaii

August 11, 2011

Overview

- Quick review of existing hardware pieces
 - Hawaii electronics.
 - Nakao-san's FTSW board.
- Primary goal this trip:
 - Integrate with Nakao-san's FTSW board and demonstrate low jitter clock distribution.
 - Will report existing test results and next testing plans.

Trigger/Timing Distribution (FTSW)

From Nakao-san's documentation:

20110805 version

Timing signals over CAT7 cables

7 ports, O1 to O7

- ACK → ACK: 254 Mbps serialized, unused
- TRG ← TRG: 254 Mbps serialized
- RSV ← RSV: pulled down to GND
- CLK ← CLK: 127 Mhz

JTAG signals over CAT7 cables

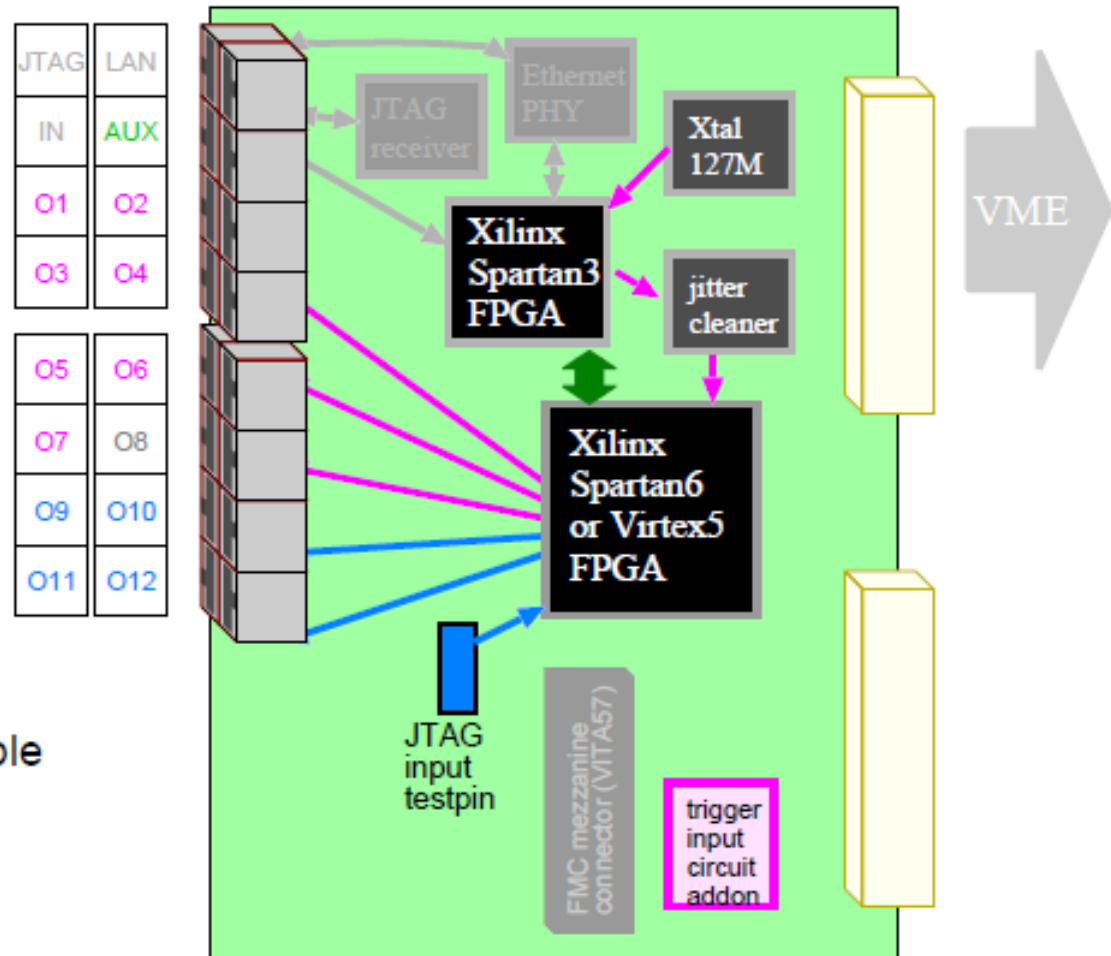
4 ports, O9 to O12

- TCK ←
- TMS ←
- TDI ←
- TDO →

Monitoring signals over a CAT7 cable

AUX port

- trgin ← copy of trigger input
- trg21 ← latched with 21MHz clock
- trgpulse ← trgin and (not trg21)
- clk21 ← 21MHz clock



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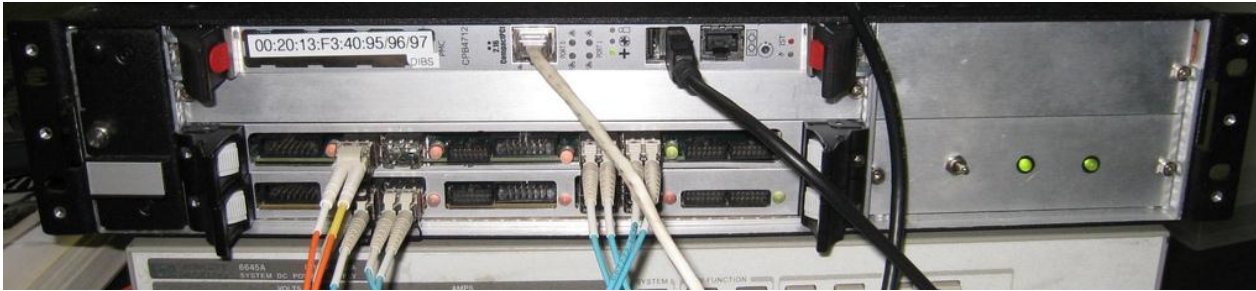
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JTAG	LAN
IN	AUX
O1	O2
O3	O4
O5	O6
O7	O8
O9	O10
O11	O12

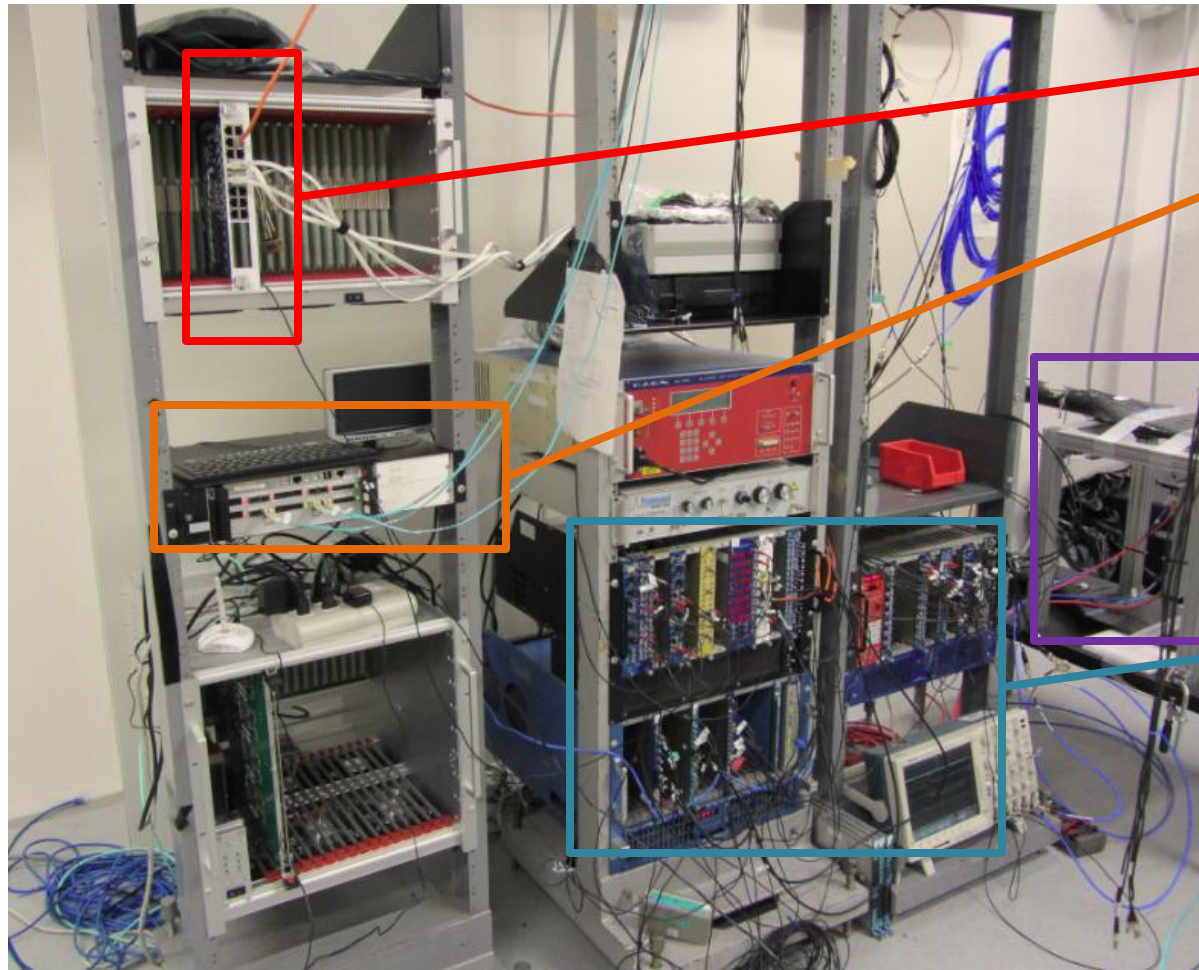


Back-End Data Acquisition



- cPCI crate (above) with custom card (DSP_cPCI, left), that receives data from front end modules.
- This crate will collect all data for the cosmic and beam tests.
 - Collects data from front-end modules by fiberoptic.
 - Collects CAMAC data via USB.

Current Testing Setup



FTSW Module

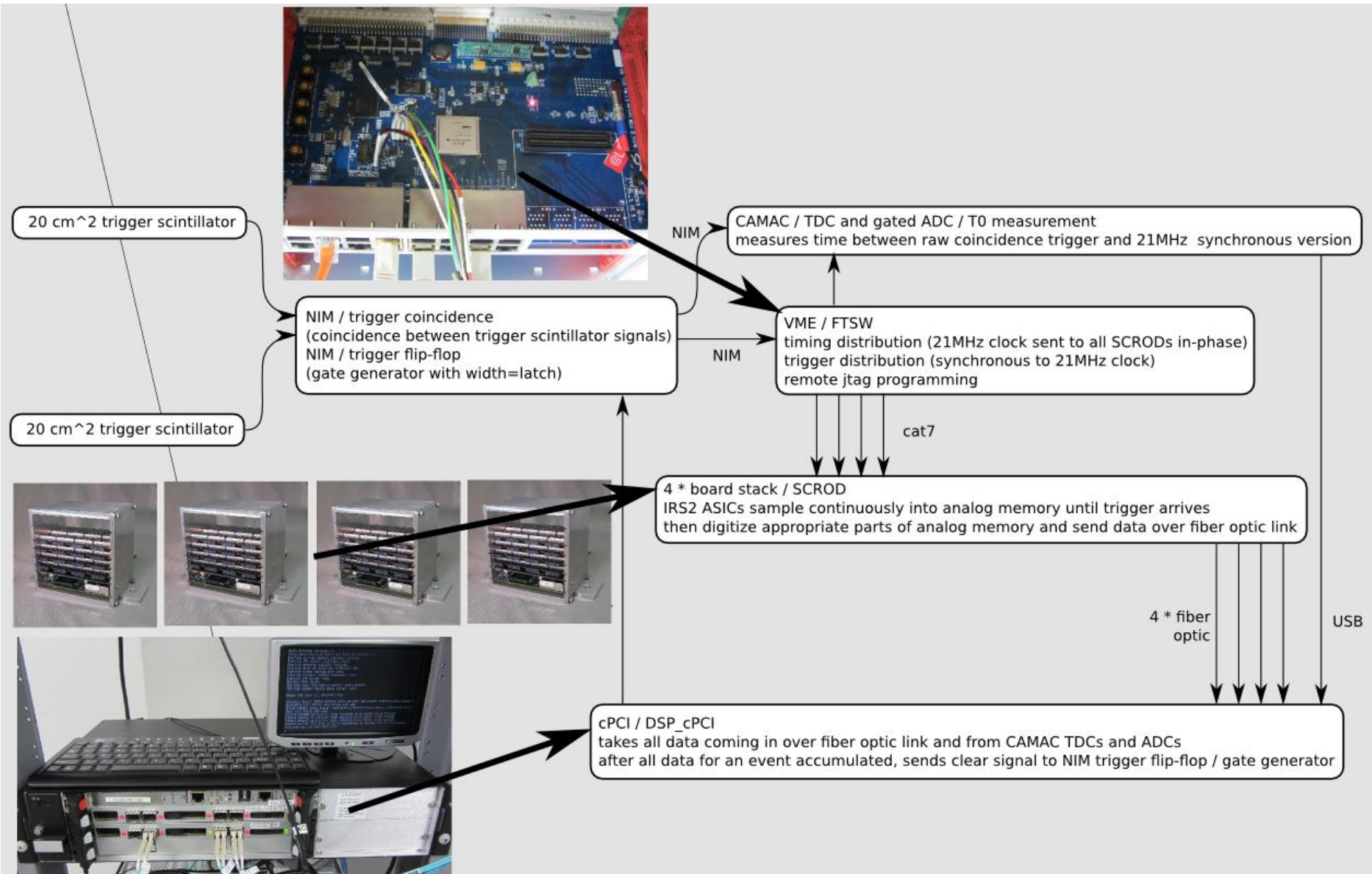
Back-end fiberoptic System

Scintillator paddles & timing counters

NIM modules & CAMAC crate

Thank you for very nice setup and use of equipment.

Cosmic Test System Diagram



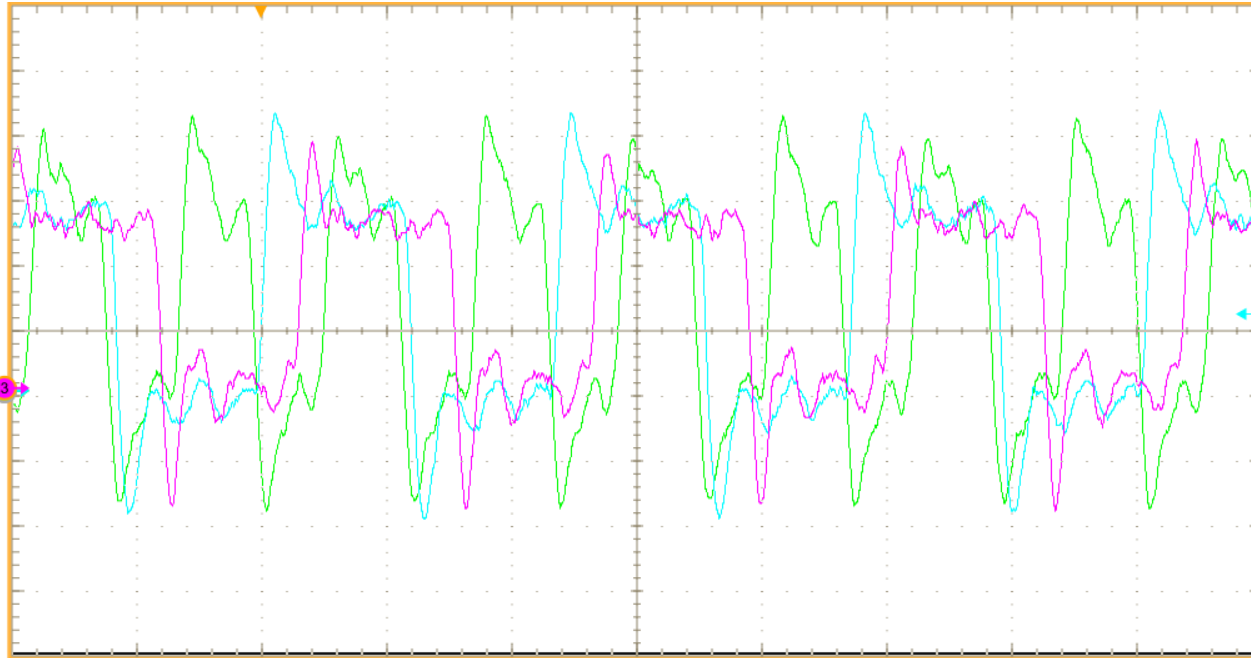
FTSW Integration Report

- Nakao-san visited Nagoya on August 5-6:
 - Provided 1 FTSW for use in our beam test.
 - Provided firmware and support in integration effort.

Initial testing:

- JTAG programming:
 - Verified that we can program front-end modules from FTSW through 15 m of flat CAT7 cable.
 - 1 at a time or multiple simultaneously.
 - Results sensitive to grounding → FTSW and front-end modules should share a common ground.
- Simple trigger distribution:
 - FTSW module can accept a NIM trigger and pass on the raw signal through 15 m flat CAT7 cable.

Front-End Clock Requirements



Front end digitizing requires three critical clocks with specific phases:

Clock Signal	Freq (rel. to sampl. rate))	Freq (@2.7 GSa/s)	Comments
Sampling track	$f_s / 128$	21.17 MHz	
Sampling hold	$f_s / 128$	21.17 MHz	<u>Must be low jitter</u>
Write strobe	$f_s / 64$	42.3 MHz	

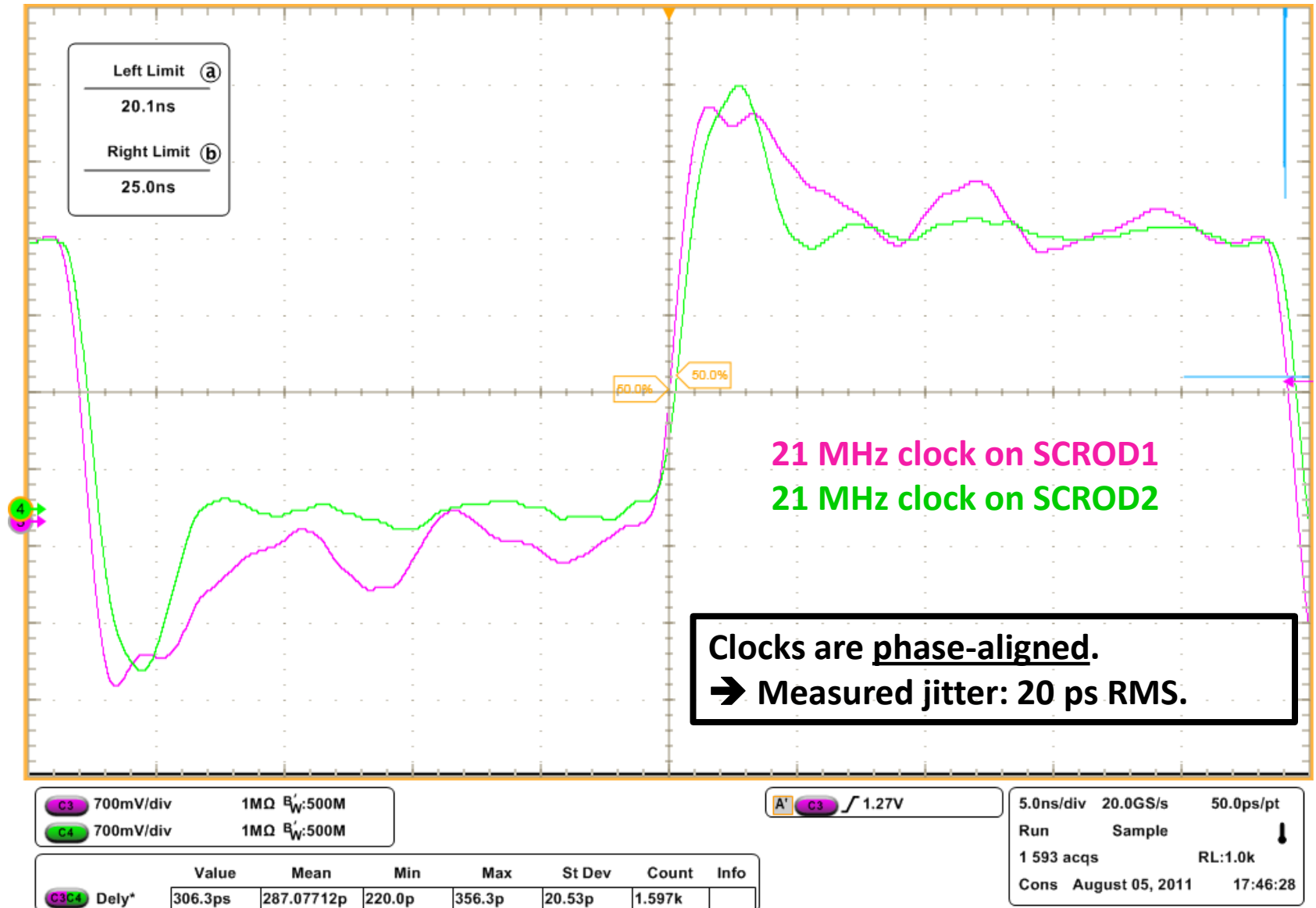
Front-End Clocks and FTSW

- FTSW delivers a 127 MHz clock via CAT7 cable to front-end modules.
- Front-end modules must generate these required clocks...
 - Clocks must be phase aligned for all front-end modules!
- Integrated Nakao-san's receiver firmware into front-end firmware to test jitter between the most critical clock signal between different front-end modules.

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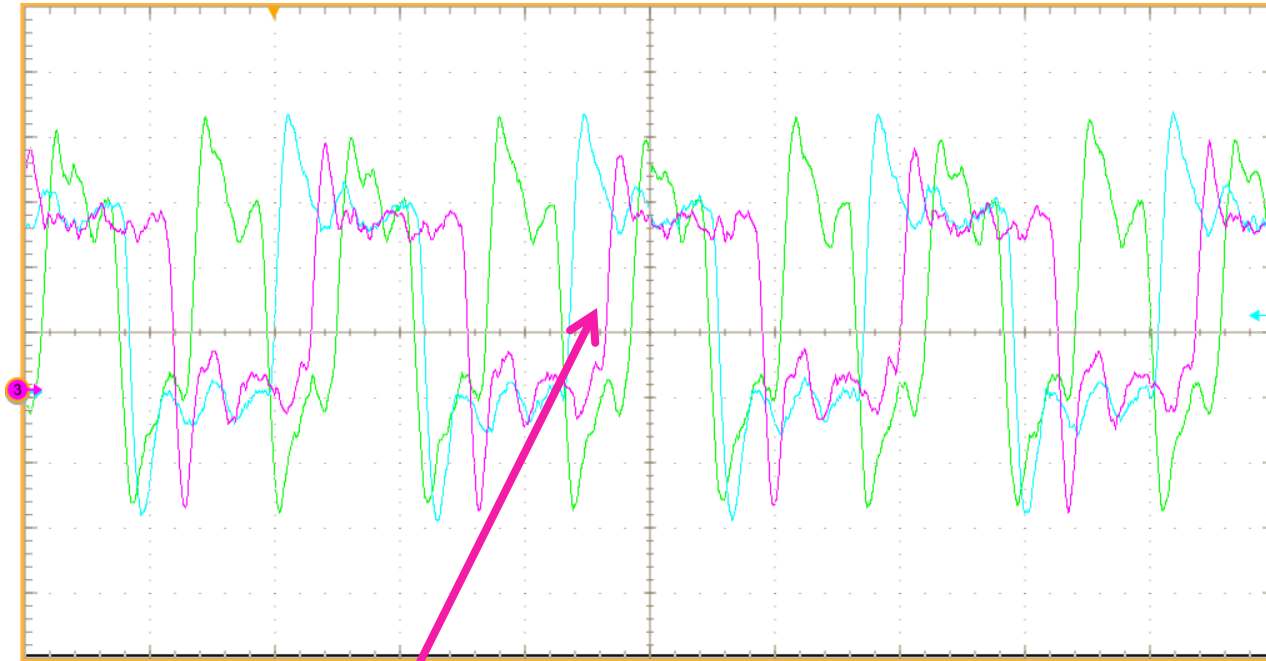
Timing Distribution Results



Backend Data Collection

- For cosmic and beam test, we must collect data from two systems:
 - Front-end modules
 - CAMAC
- Proper synchronization between events is critical!
- Strategy: veto new NIM triggers until we've read out all relevant data for each event.
 - System is set up and nominally working, with FTSW trigger distribution.
 - Currently limited to ~50 Hz instantaneous event rate (with a 4:56 spill duty cycle, ~100k events per 8 hour shift).

Timing Alignment Between Front-end and Global Trigger

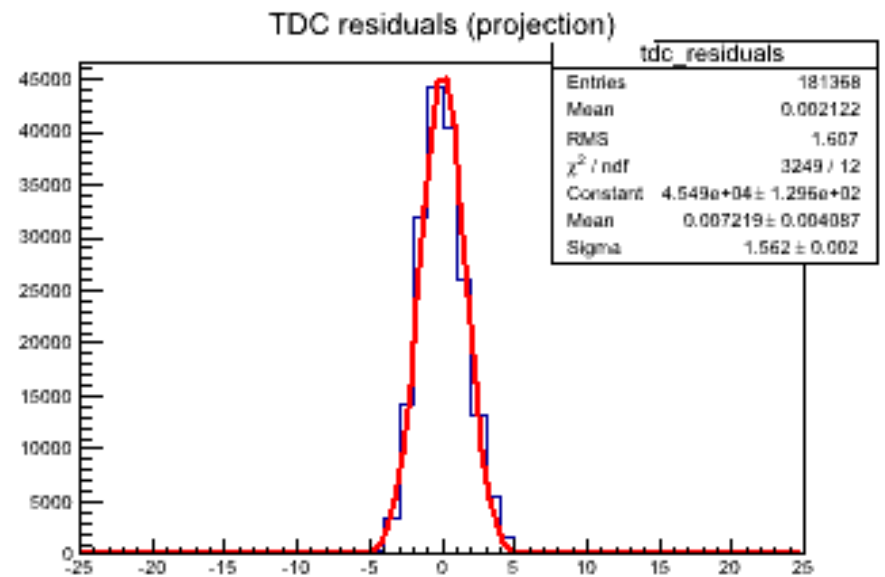
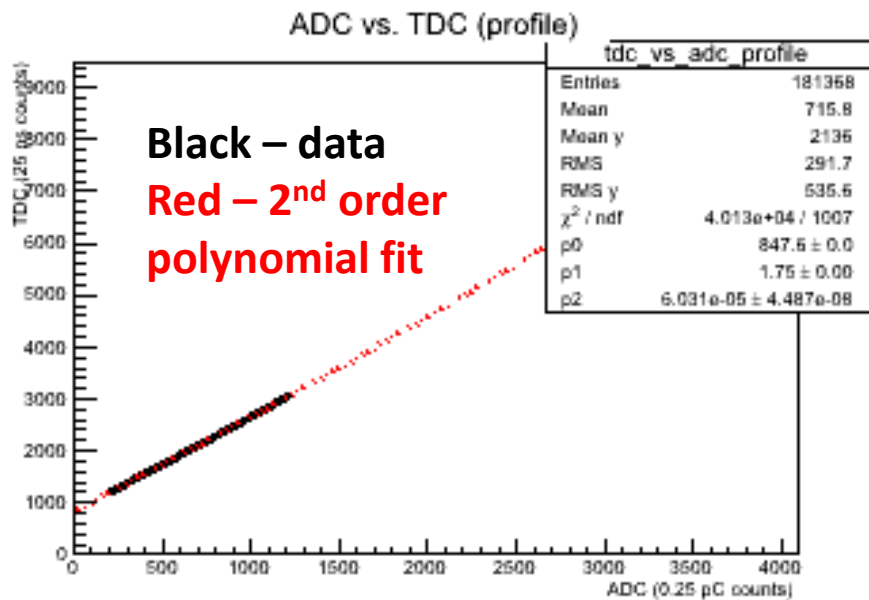
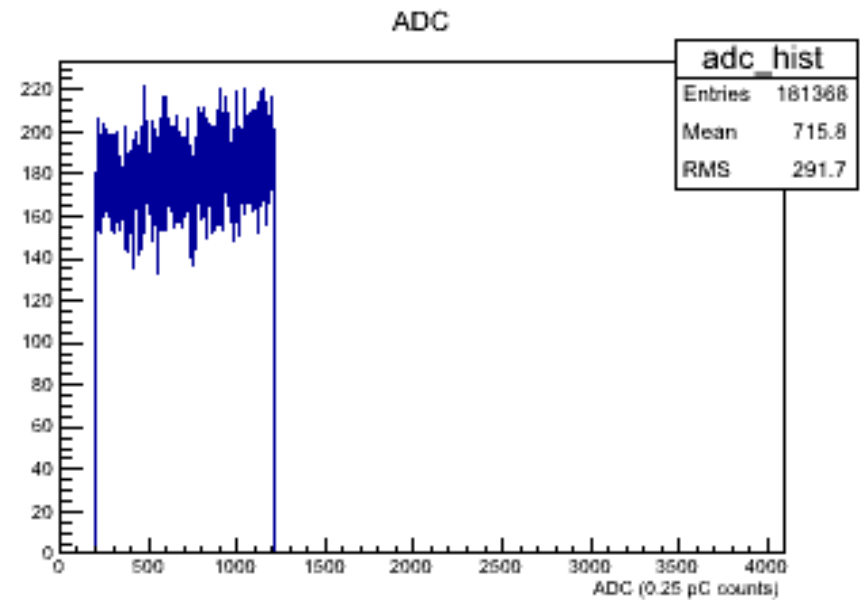
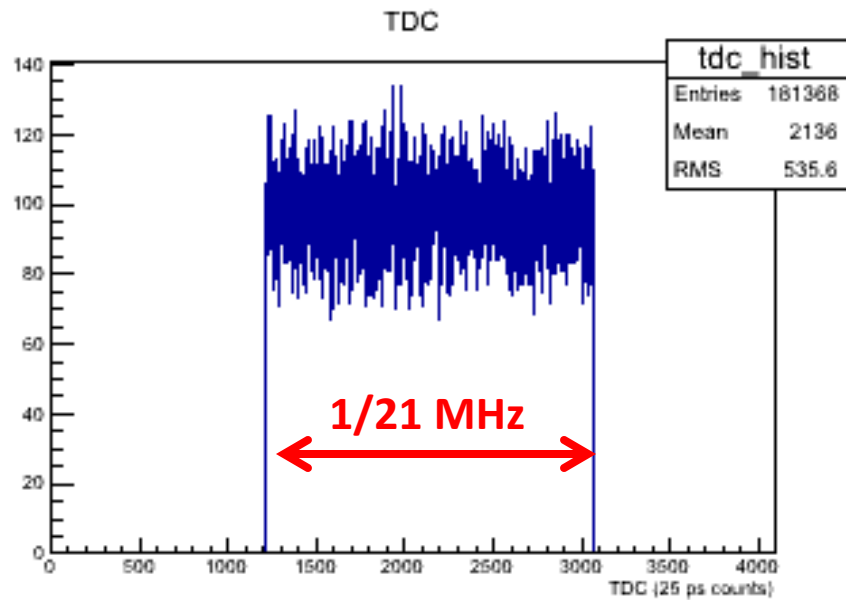


Front-end electronics measures timing relative to these clock edges...

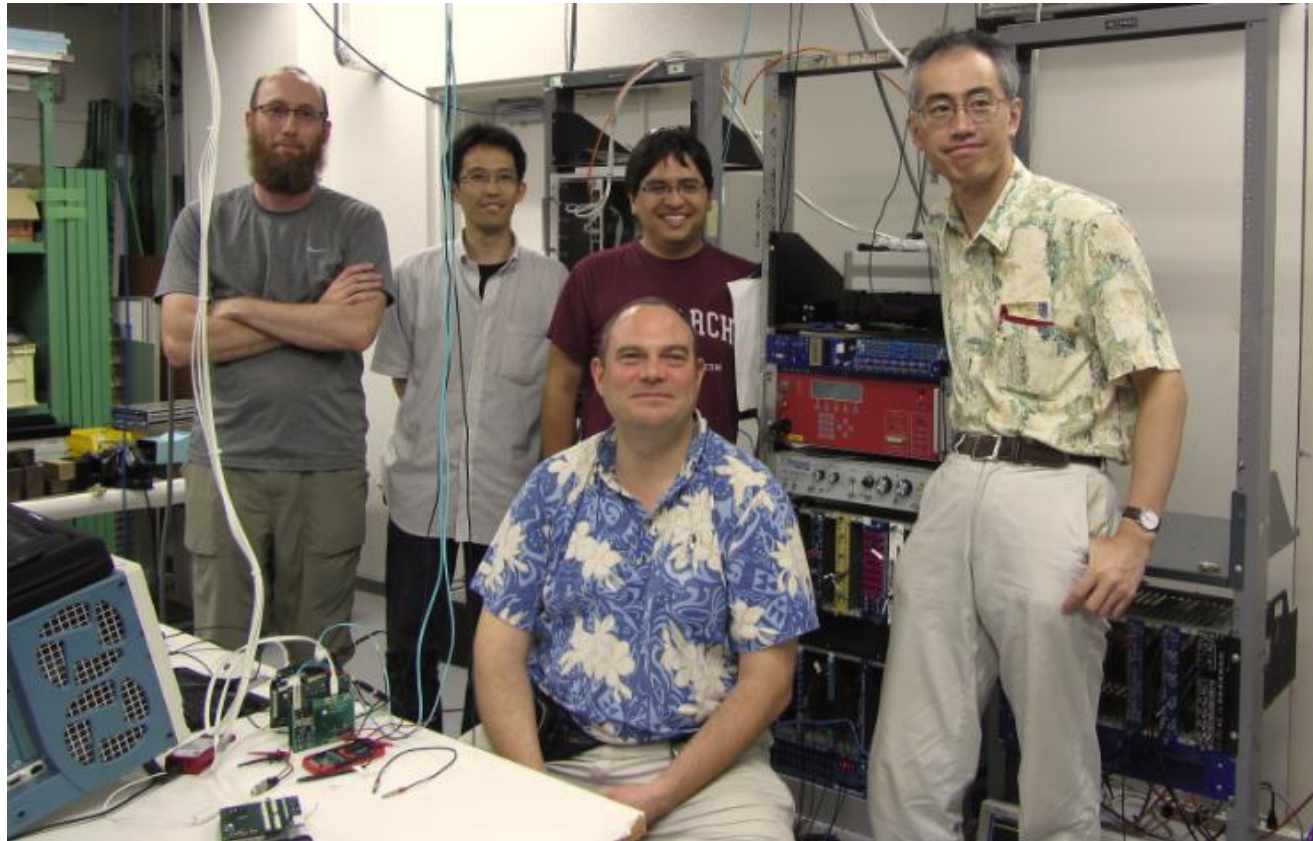
But for beam test and cosmic ray test we need to align to the global trigger.

Timing Alignment w/ Global Trigger

- FTSW provides two signals that can be used for alignment:
 - A copy of the trigger synchronous with 21 MHz clock.
 - The trigger starts a TDC, this signal stops the TDC.
 - A signal that rises asynchronously with trigger and falls synchronously with 21 MHz clock.
 - This signal is sent to an ADC, which effectively measures its width.
- These TDC and ADC values are readout by CAMAC USB crate controller.
 - Measuring both will give some redundancy, possibly improve errors (or at least provide a cross check).



FTSW Summary



➔ **With some care required (timing in firmware, grounding between modules, and cable quality), FTSW meets our needs for timing and trigger distribution as well as remote programming.**

Next Steps

- Integrate readout of real front-end data with fiberoptic protocol (currently done by USB).
- Verify global timing alignment scheme.
- Try measuring timing resolution between different front-end modules using MCPs.
 - Either cosmic timing counters or SL10s with laser input.
- Still lots of firmware/software to integrate and debug...
 - ...but we've made lots of progress during the past week.