



University of Washington
VISUAL TECHNIQUES LABORATORY
OPERATIONS NOTE

ON - 150

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date 7/8/91 rev. date

subject May 13 Frosh Pond Chirp Test

To: Durnand File
From: B. Egaas
Subj: May 13 Frosh Pond Chirp Test
Date: 8 July 1991

This test was the followup to the in-air tests of 9 May 1991. The same analog chirping circuit and Gespac data logging system was used. The only difference was that this experiment was done using transducers in water instead of speakers in air. Because the speed of sound is about 4 times faster in water than in air, we expected the results to be 4 times worse, with range residues on the order of 10 cm. We also expected severe multipath problems.

Roger Lord, Ken Young, and I conducted the test in Frosh Pond on 13 May. The fountain was on, providing an additional noise source. We took data at five distance around the pond, chirping at one transducer and logging data at the other (see Fig. 1, next page). Datafiles are listed in the laboratory notebook.

The signal output of the power amp appeared degraded. Figures 2 and 3 show the received pulse at 0.1, 2.3, and 52.7 m. Note the received signal is barely above quantization noise at longer ranges. The signal was far below the levels we found in our February single frequency pond test. Roger had replaced the output transistors before, and it seemed they needed replacing again.

Despite this problem, we calculated correlations with a replica taken from the transmitting transducer terminals. As with the in-air tests, jitter from the chirping circuit showed up when more than one file was taken at a given distance. Table 1 shows Ken Young's Quattro analysis, this time showing residues of as much as 22 cm. Fig. 4 shows the calculated delay vs. actual separation. A best fit line gives a speed of sound of 1445 m/s, a value which is reasonable.

The remaining plots show the correlations for all the received signals, again computed in Matlab. In particular, the first data taken at 13.8 m shows a nice multipath characteristic.

Conclusion

The chirping worked in water, but low source level and jitter problems degraded performance. The range resolution is approximately 20 cm in the worst case.

FROSH POND CHIRPING RESULTS

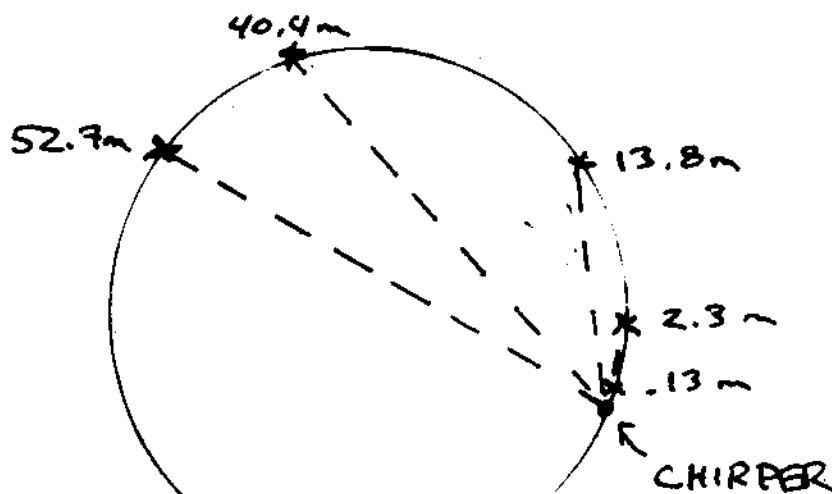
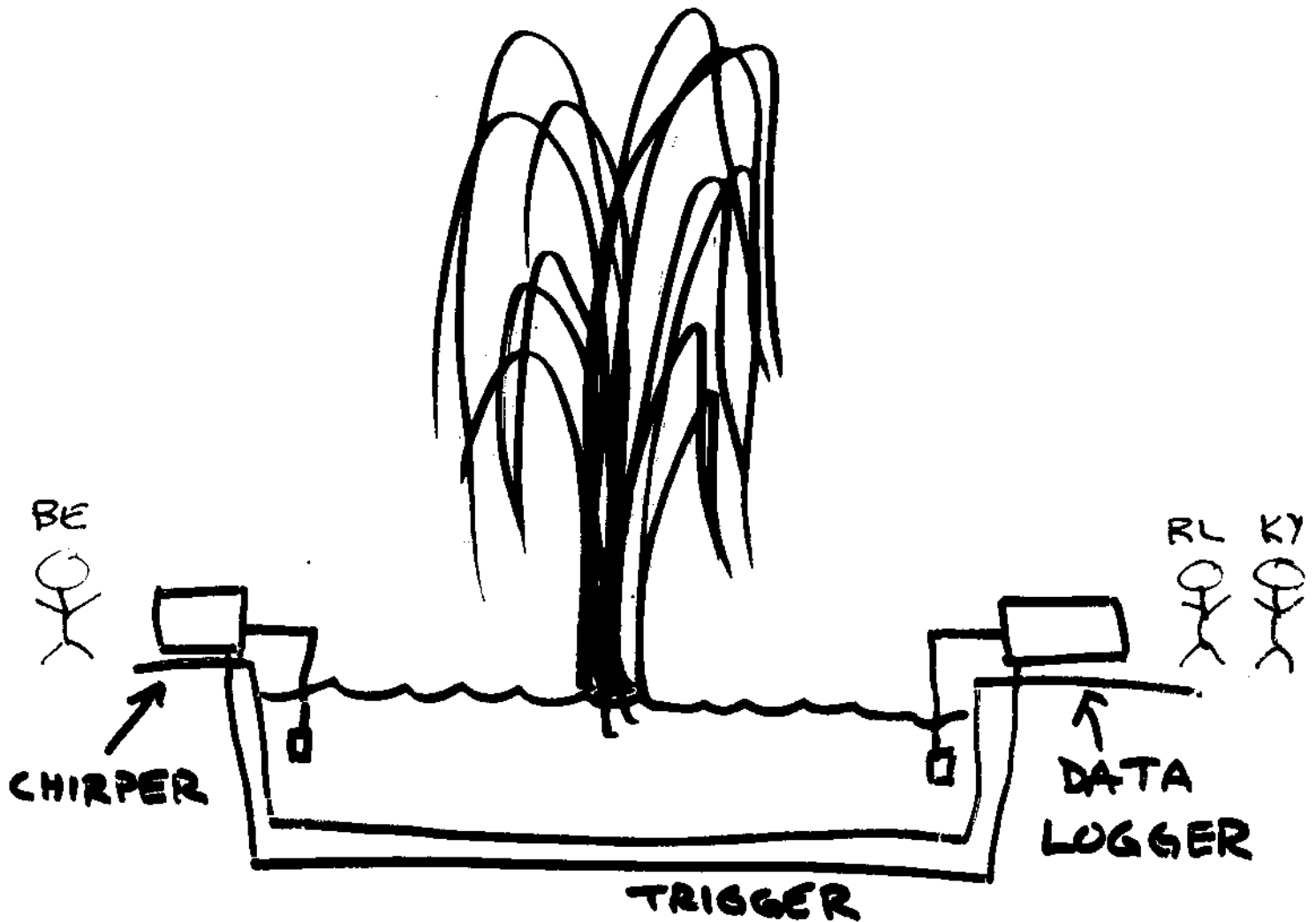


Fig. 1

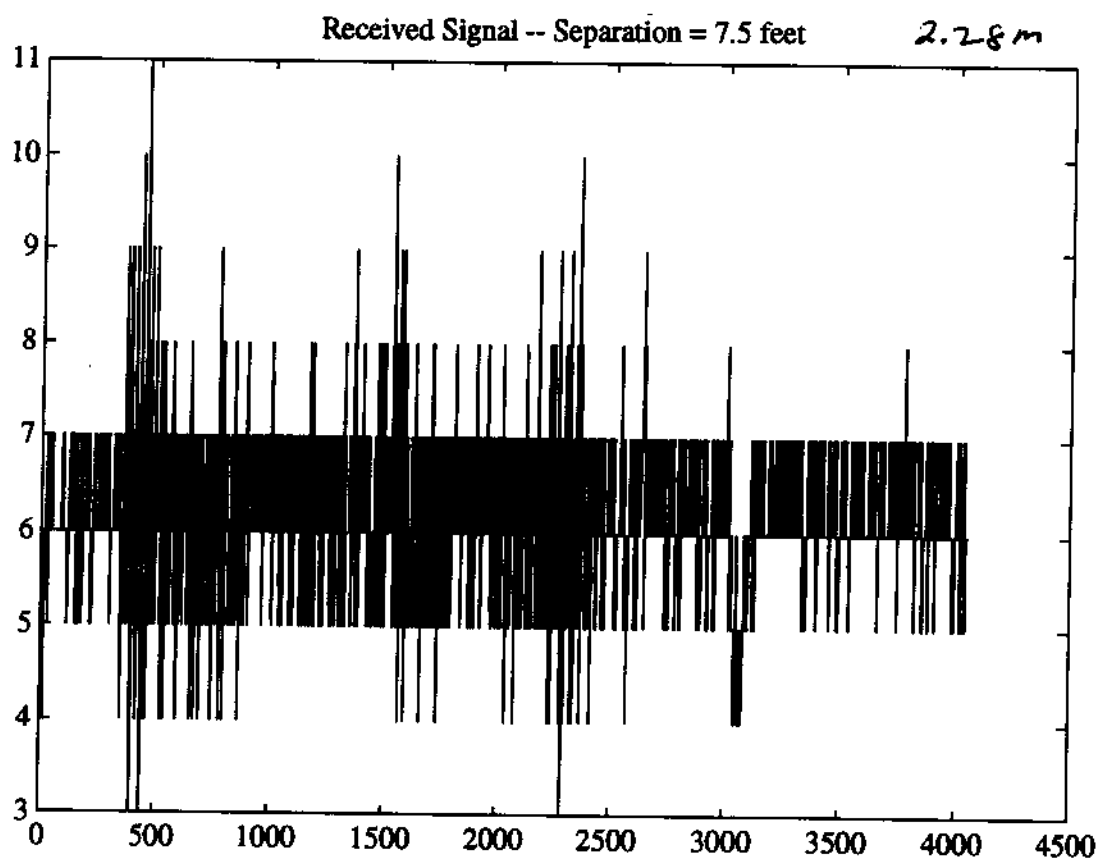
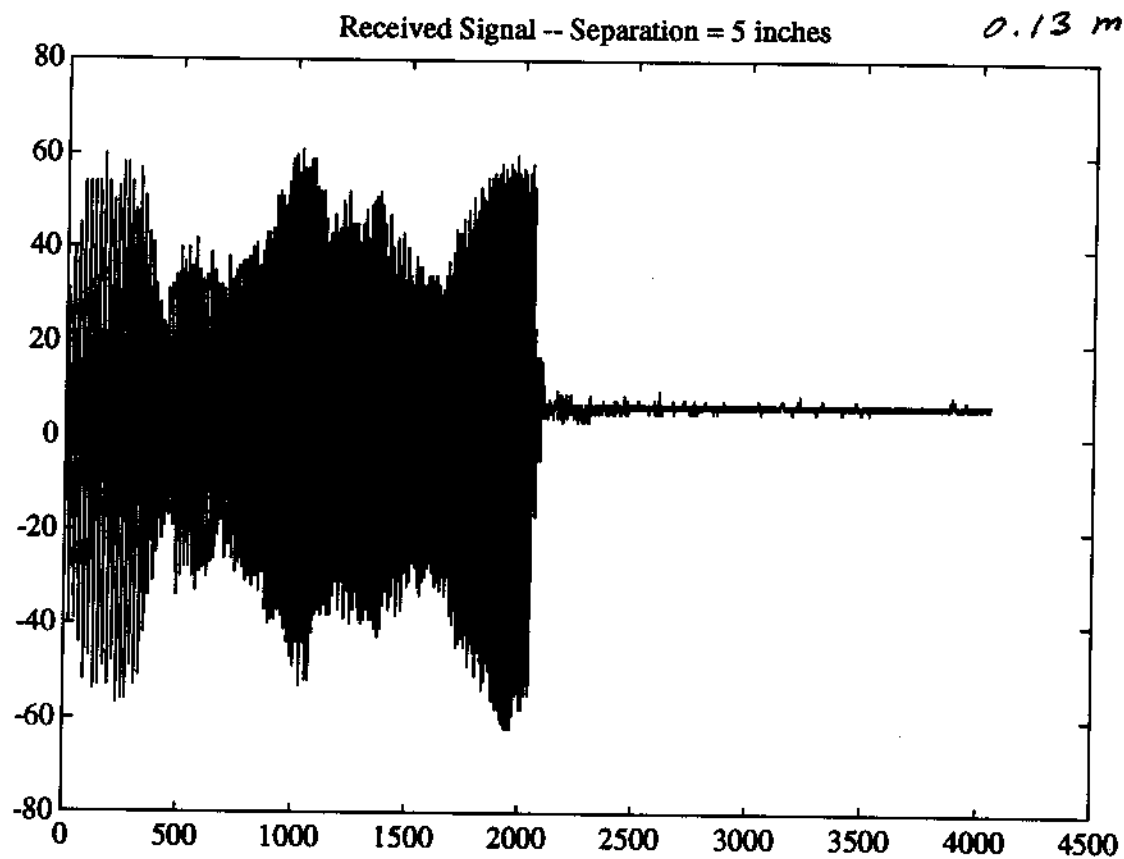


Fig. 2

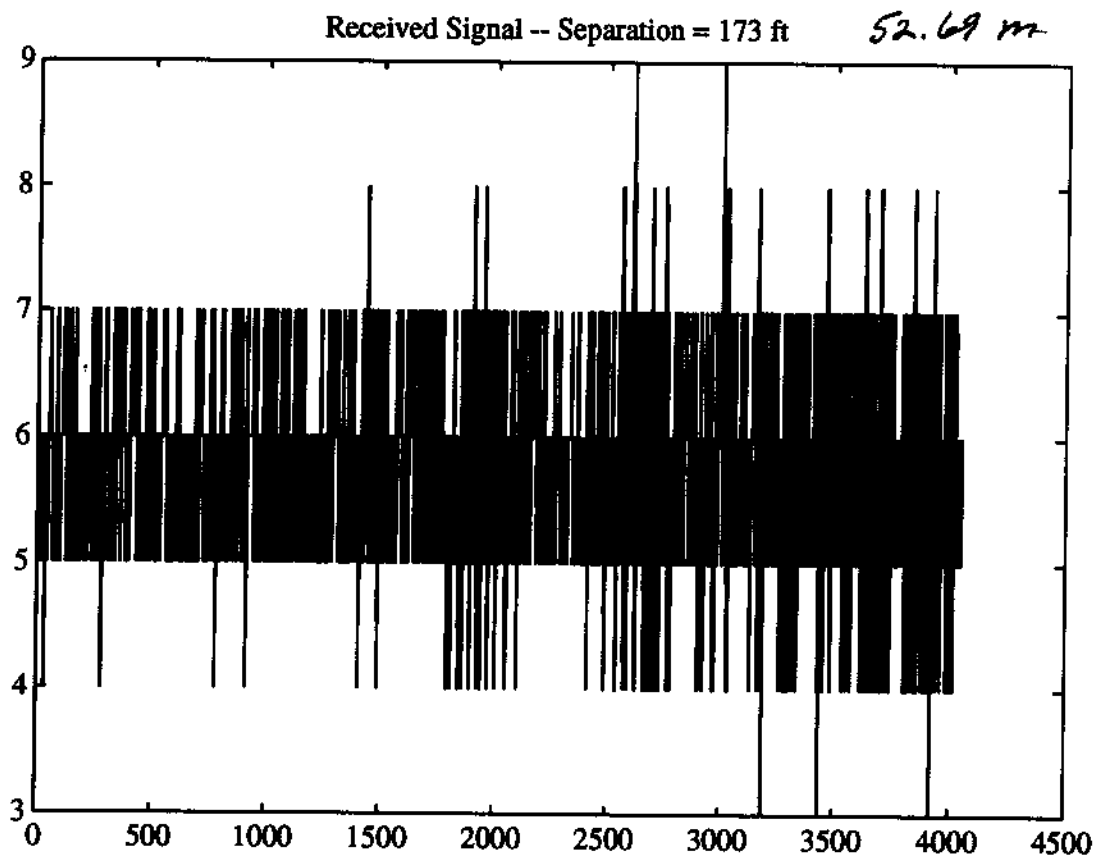


Fig. 3

Data from 13 May/91

Chirps in pond with fountain running.

and convolution to determine time.

distance time(ct) time(sec)

0.13	33	0.000165	-0.066	Regression Output:all	
2.28	370	0.00185	0.219588	Constant	-0.1745
13.81	1925	0.009625	-0.07203	Std Err of Y Est	0.113186
13.81	1922	0.00961	-0.09371	R Squared	0.999977
40.36	5606	0.02803	-0.0185	No. of Observations	8
40.36	5599	0.027995	-0.06909	Degrees of Freedom	6
52.69	7323	0.036615	0.060705		
52.69	7320	0.0366	0.039023	X Coefficient(s)	1445.451
				Std Err of Coef.	2.82335 0.001938

Note that time for 40.36 m point is from first peak (smaller)

Now the fit is good. The error is .2% which is about right!!

Regression Output:last 2

Constant	0.174984
Std Err of Y Est	0.027313
R Squared	0.99999
No. of Observations	4
Degrees of Freedom	2

X Coefficient(s)	1434.541
Std Err of Coef.	3.17776

The last two distances now give a decent velocity!!

Table 1

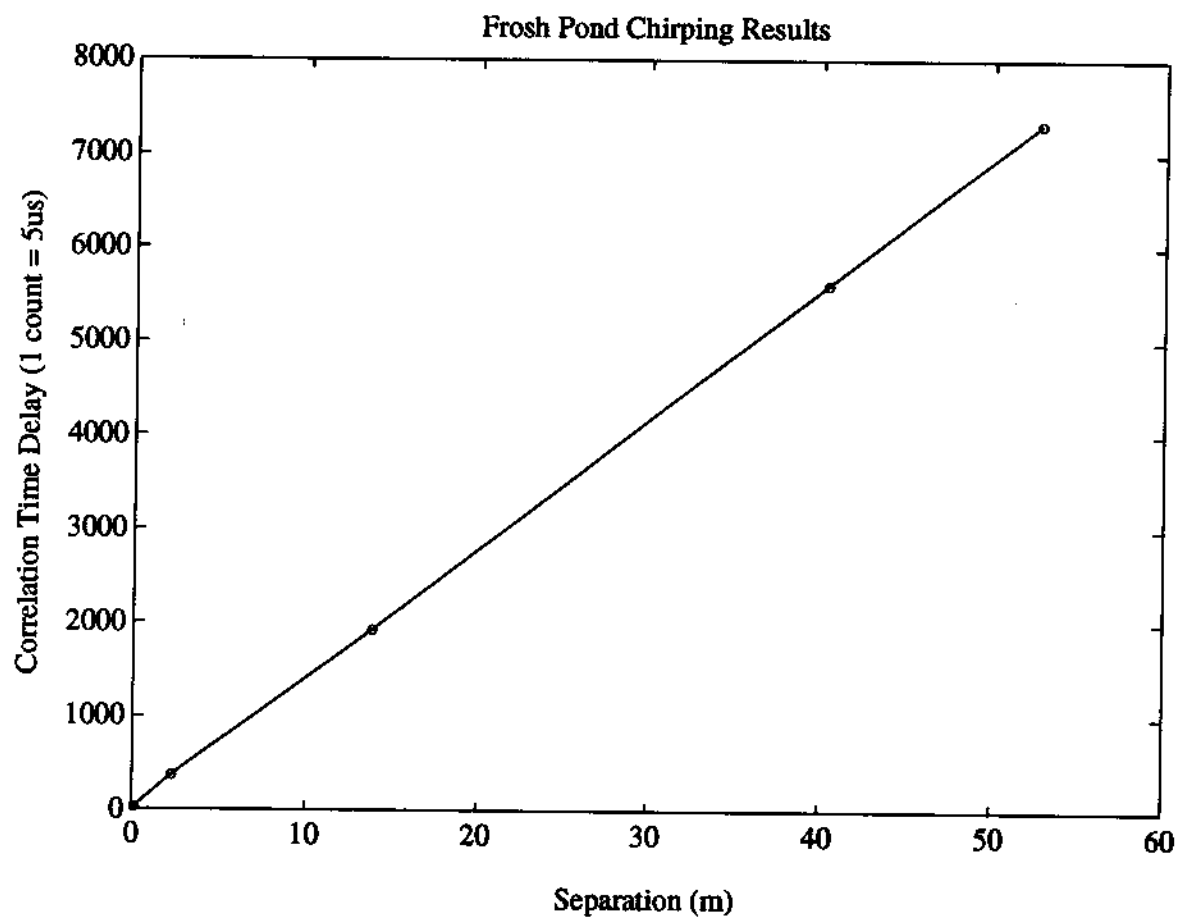
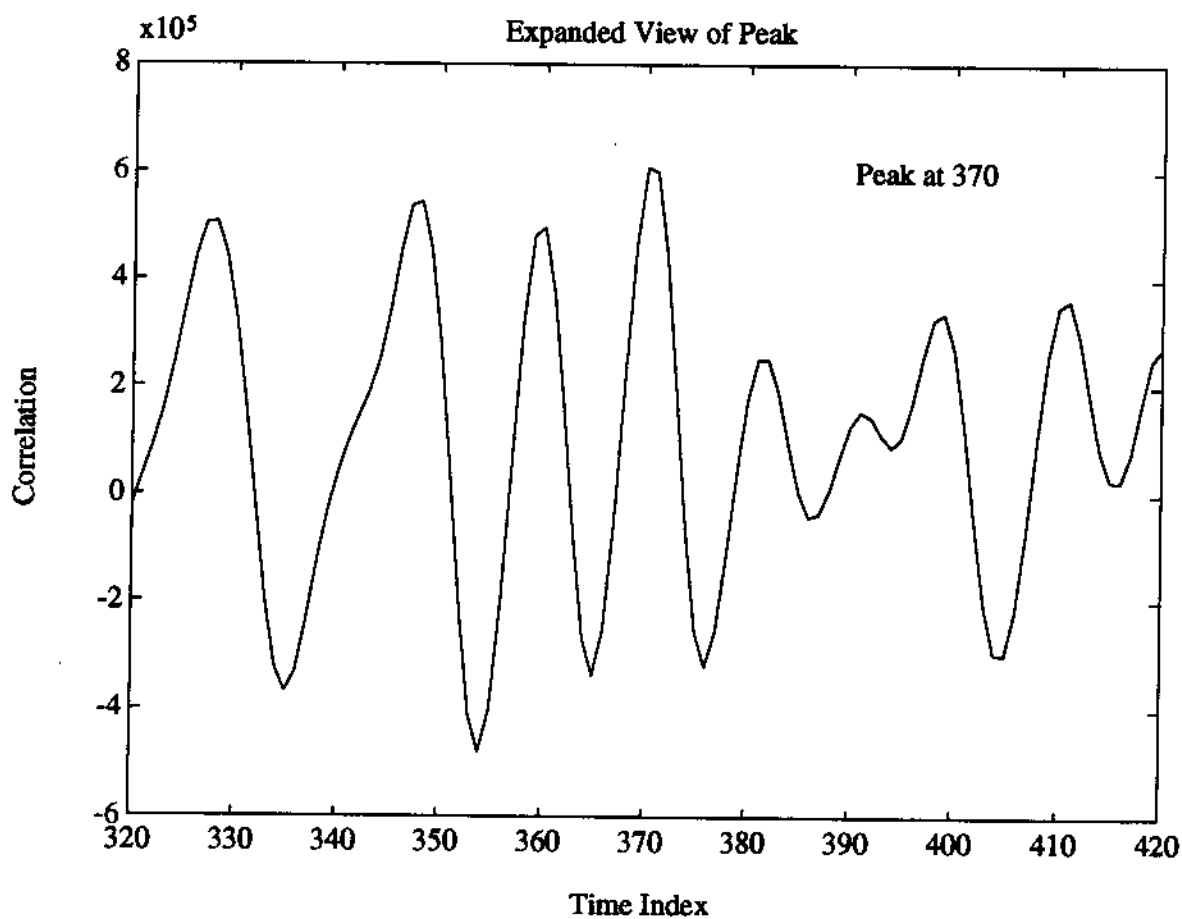
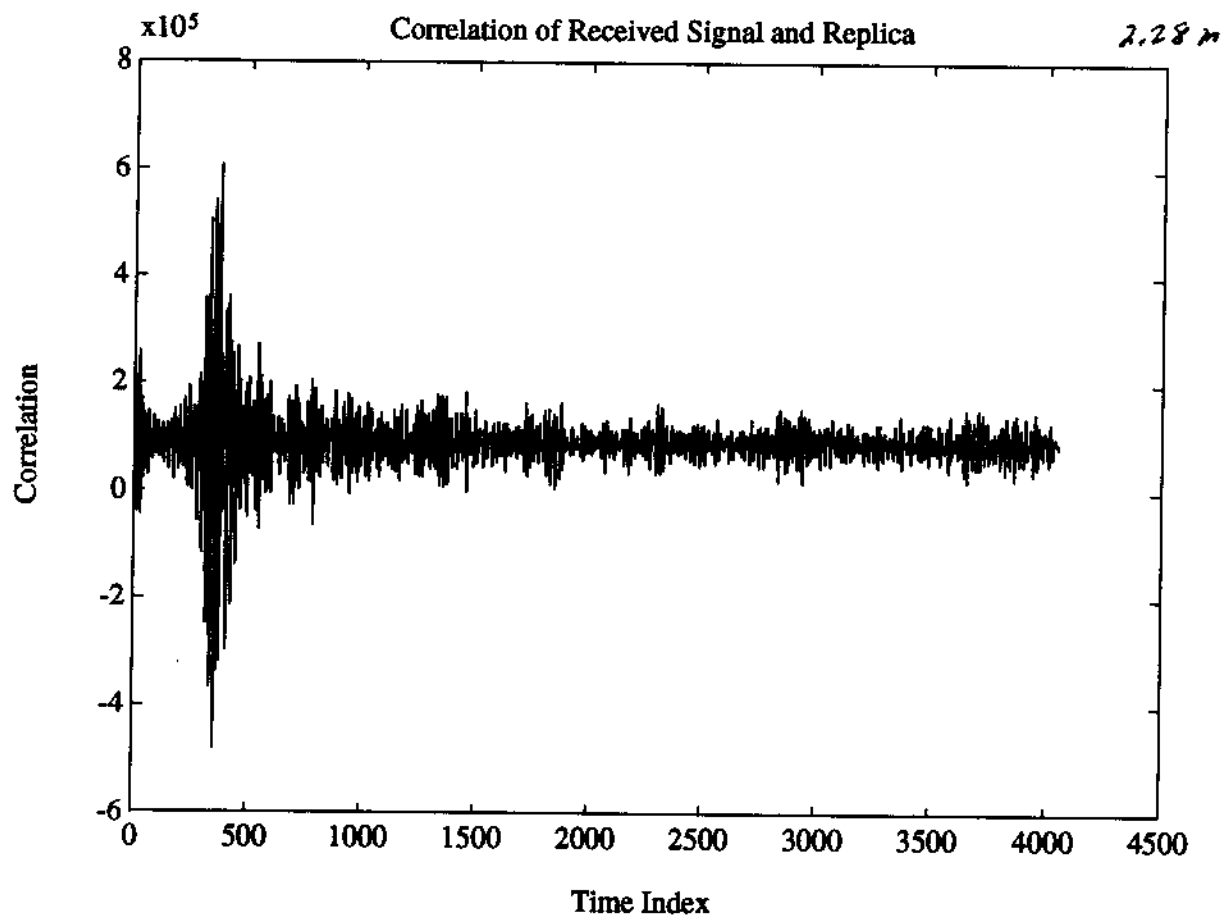


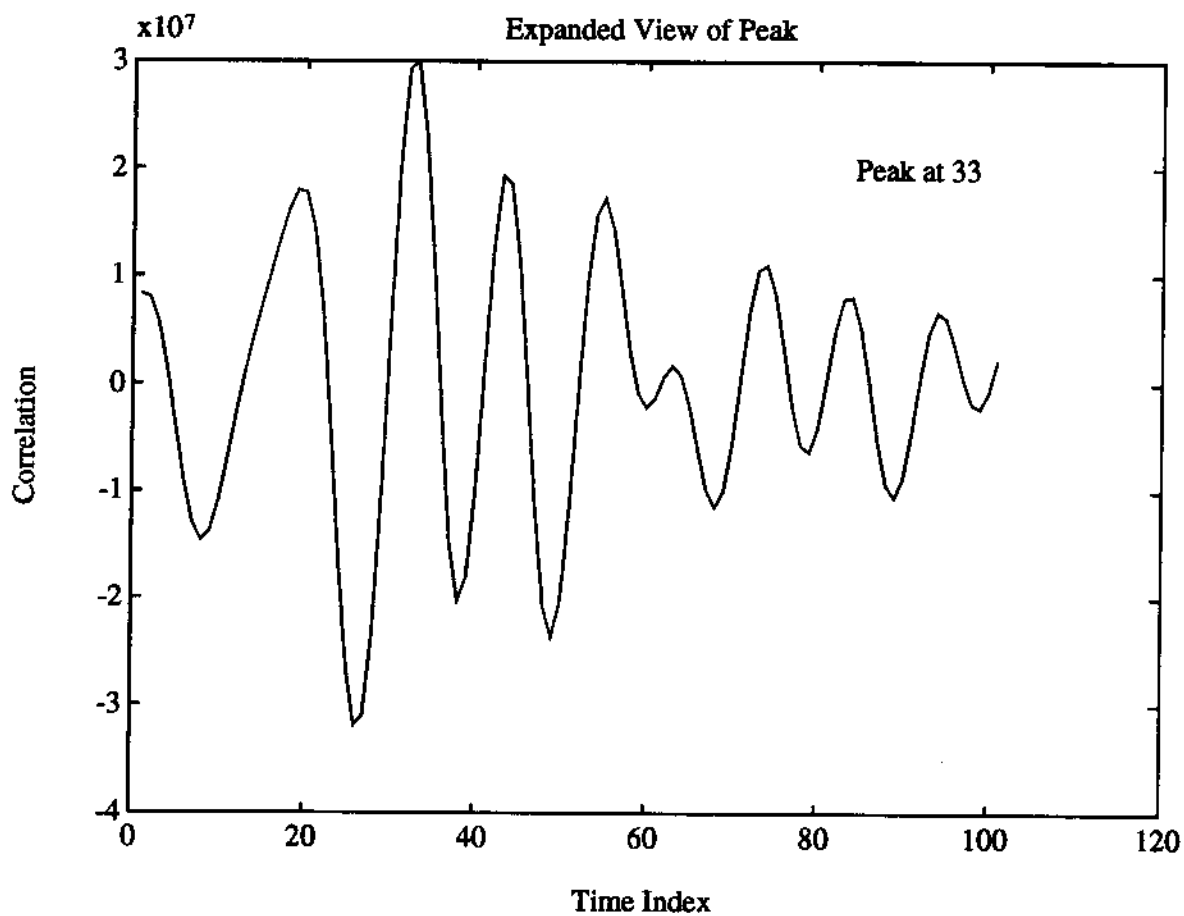
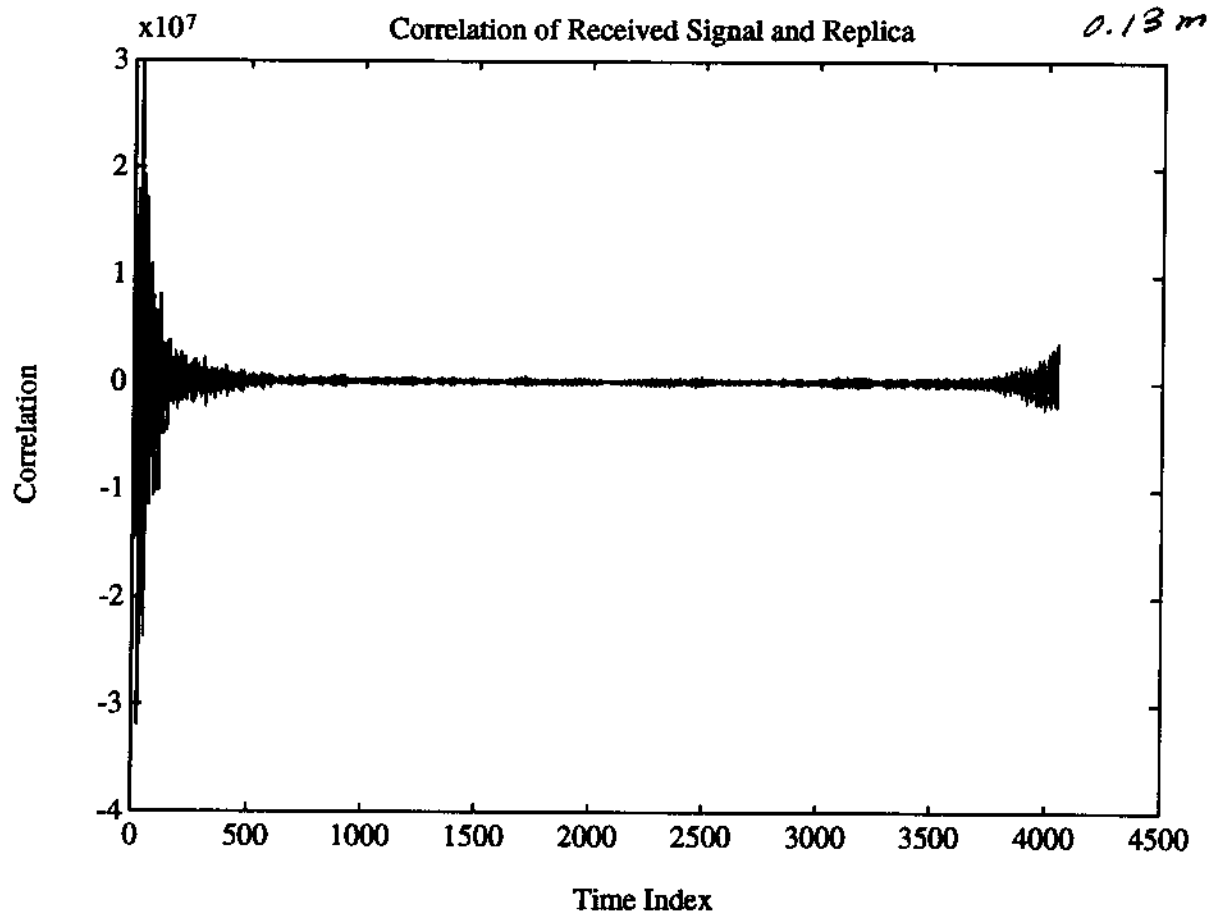
Fig. 4

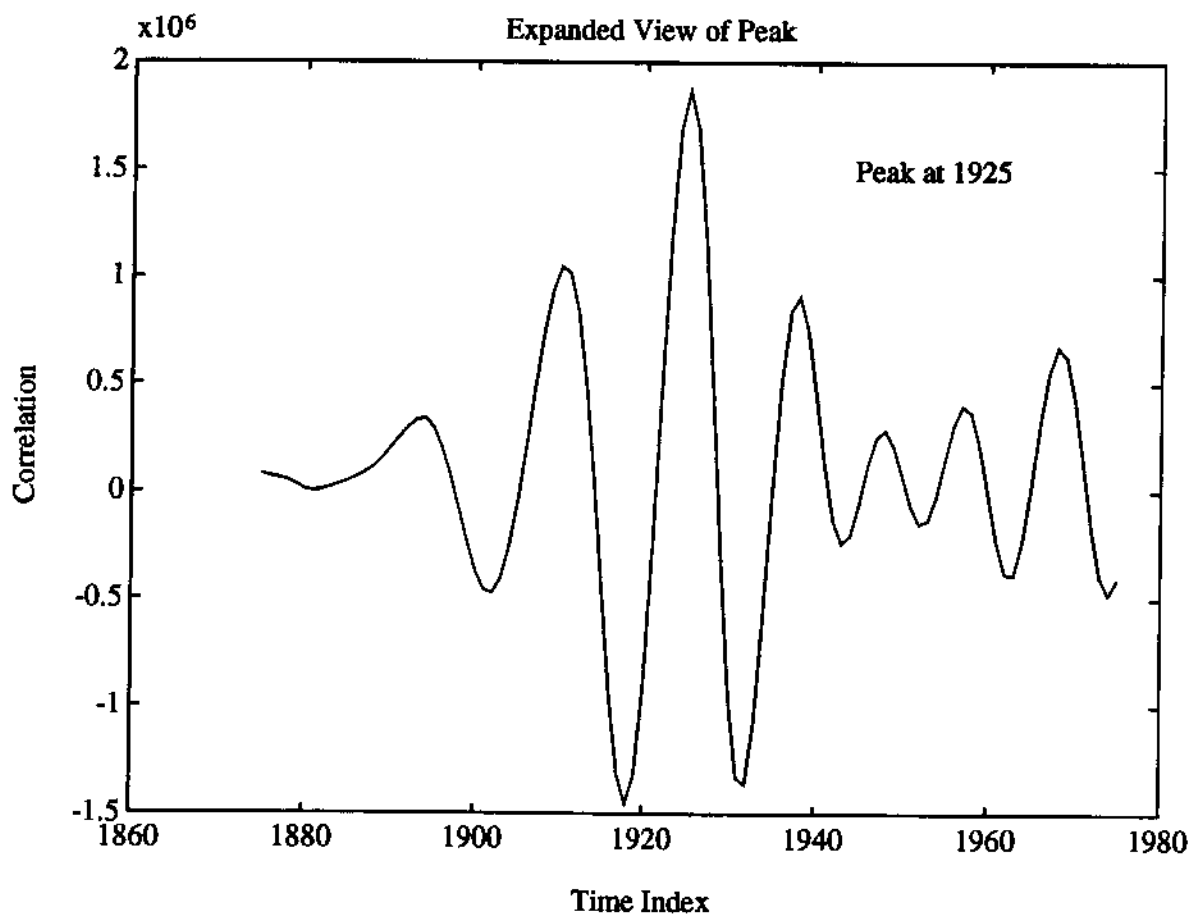
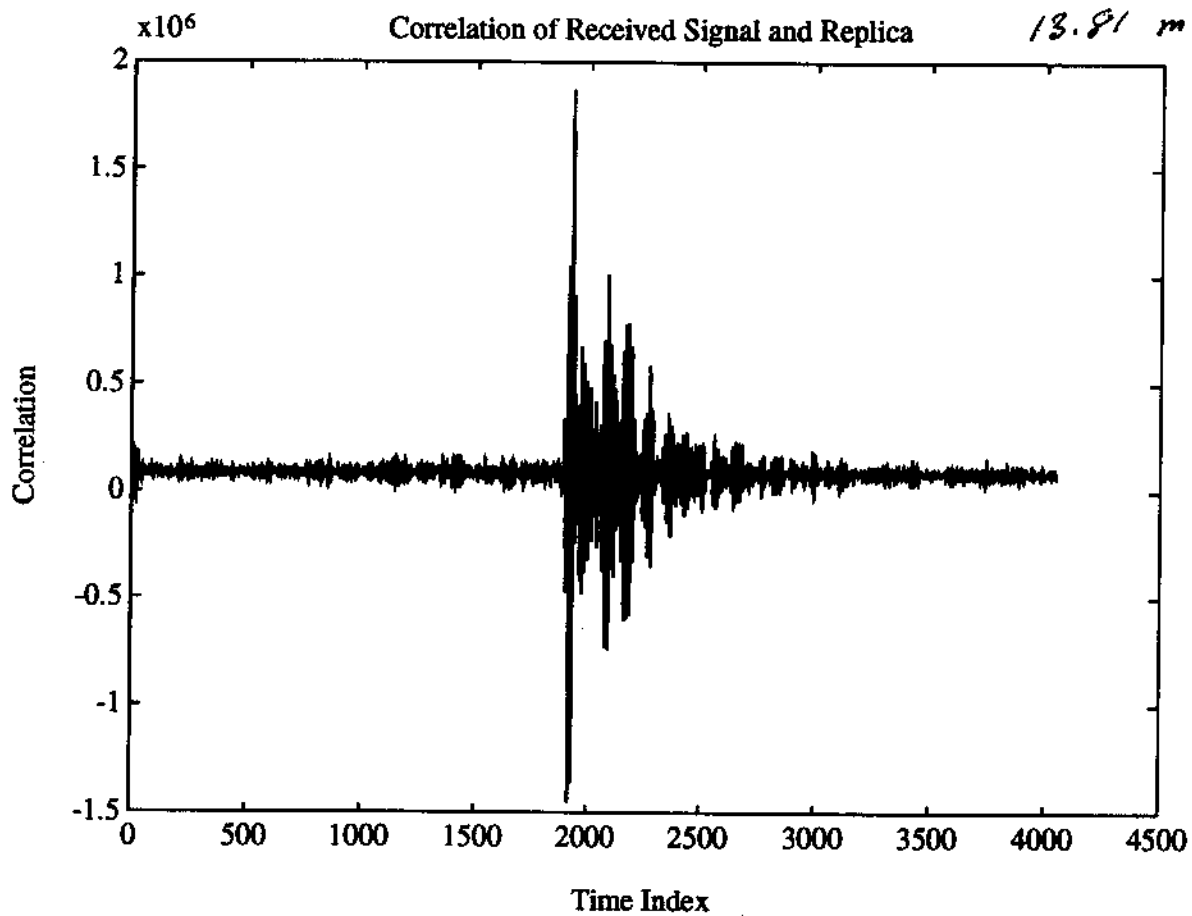
Frosh Pond
Chirping Test

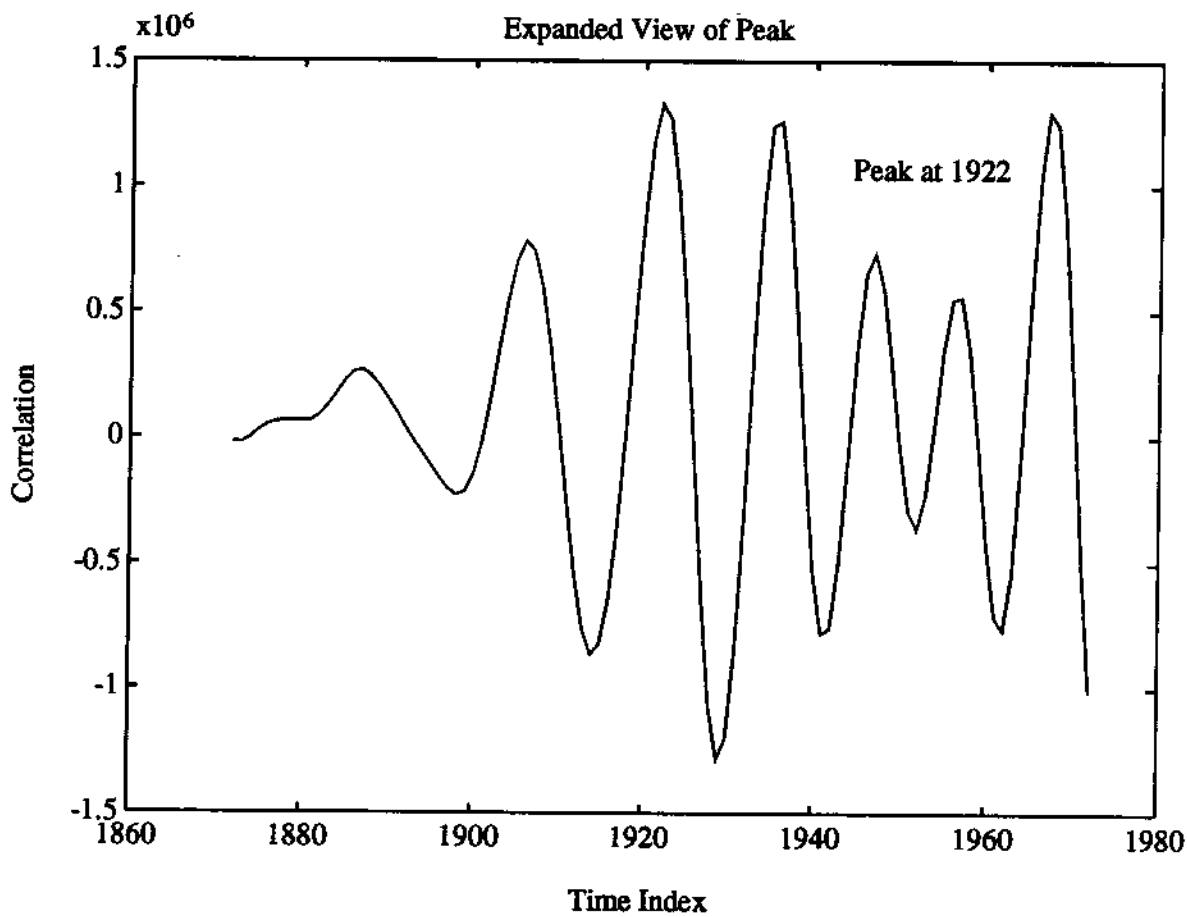
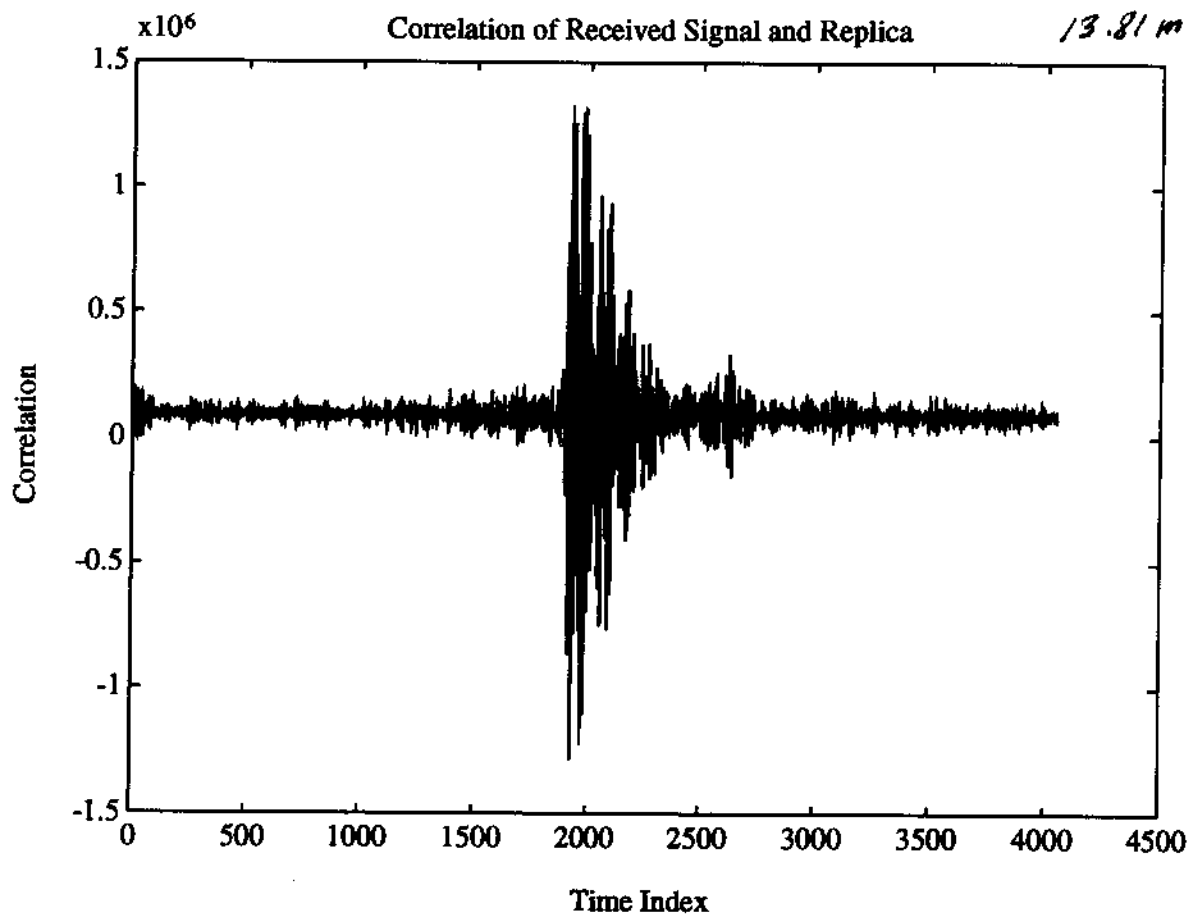
Results
of Correlations

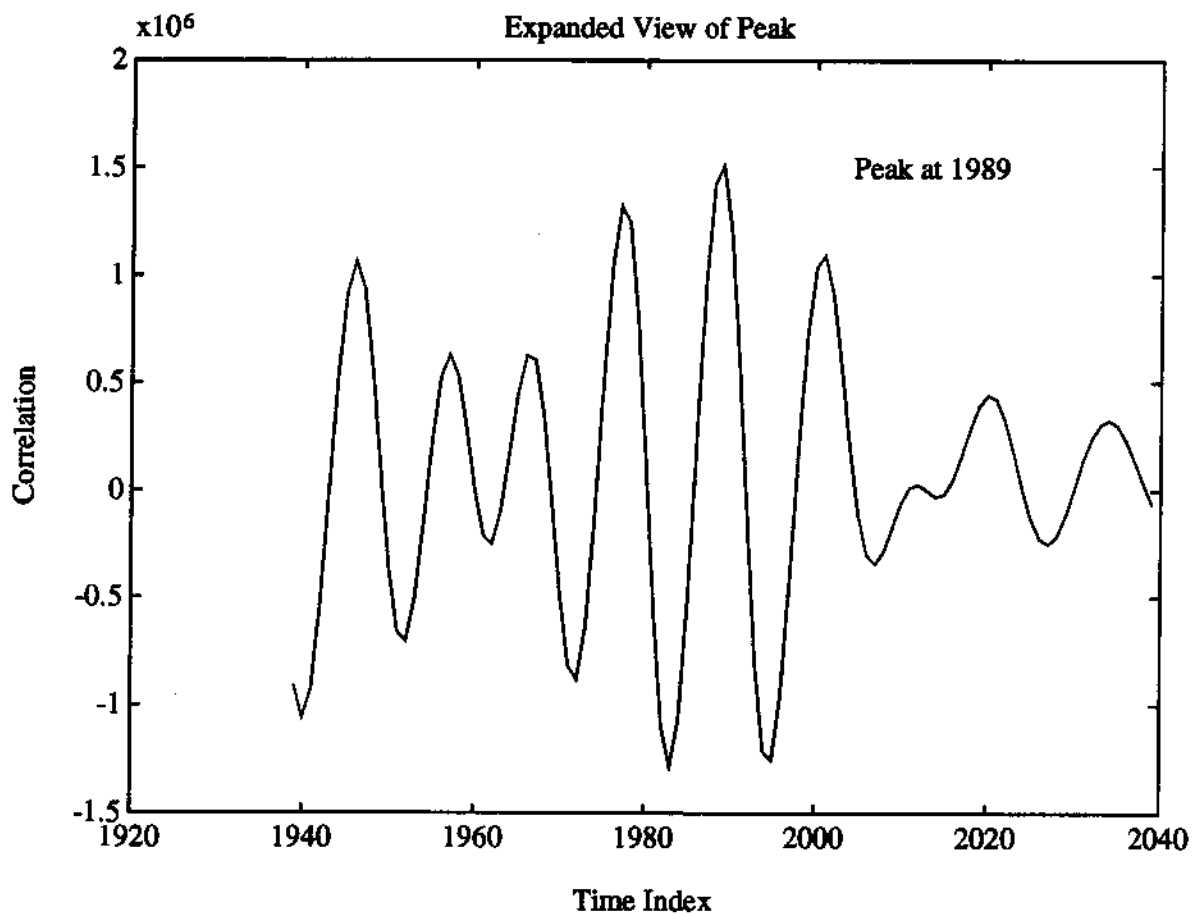
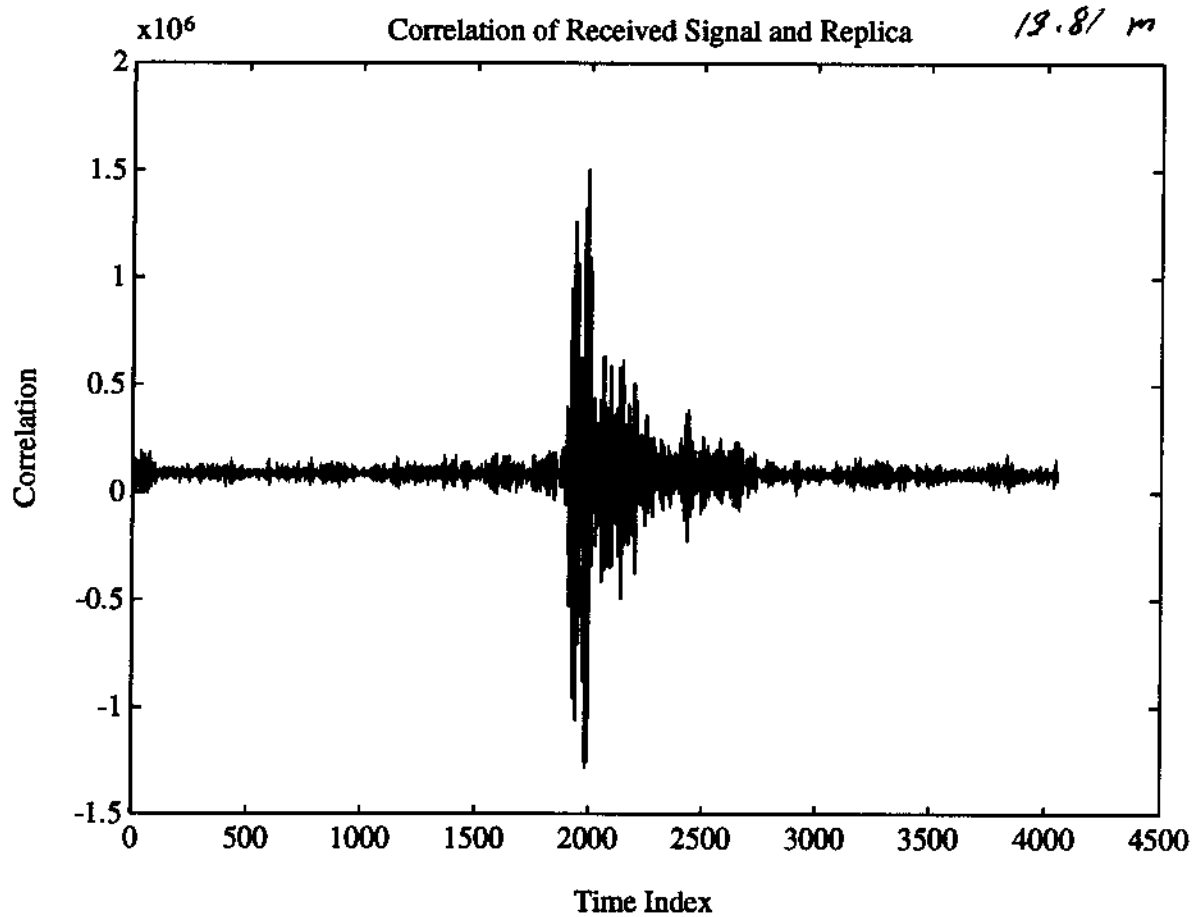
Data Taken 13 May 1991

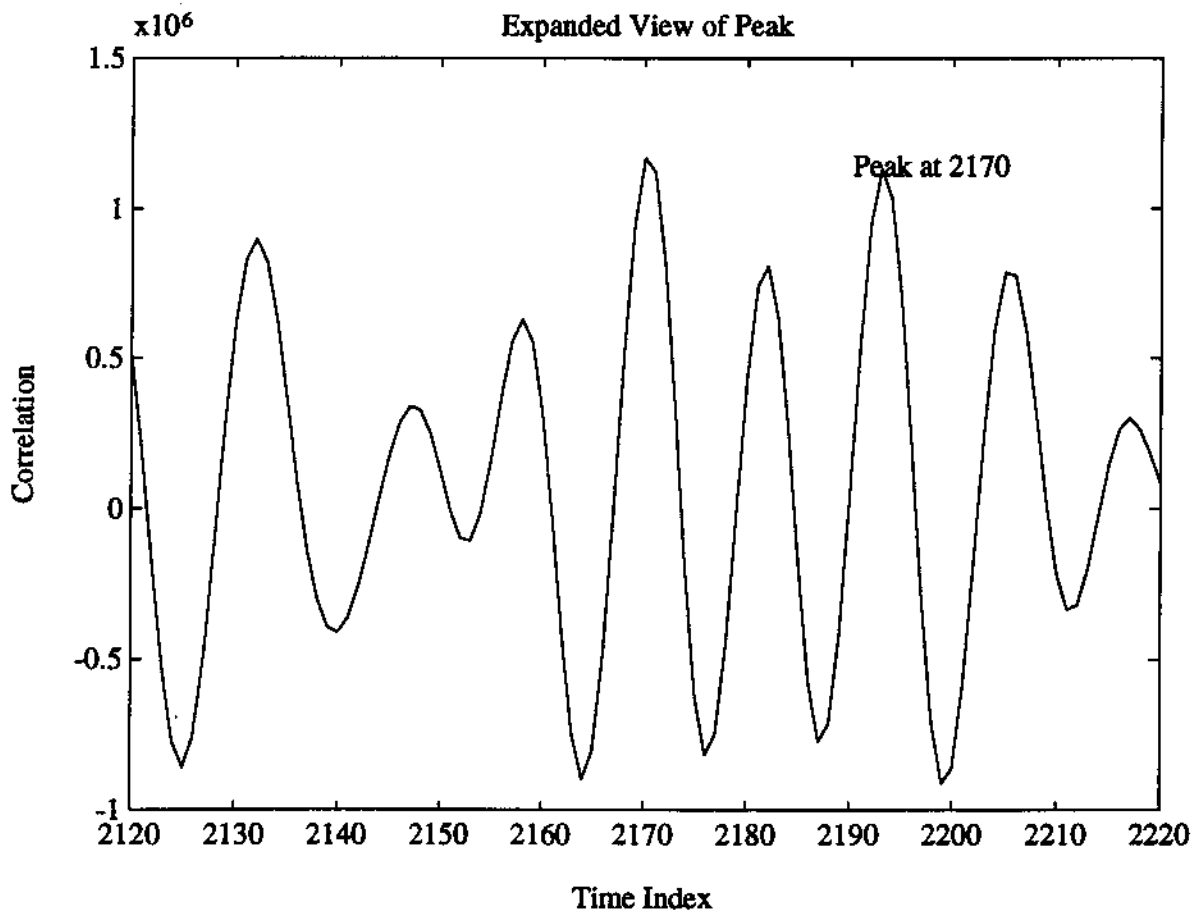
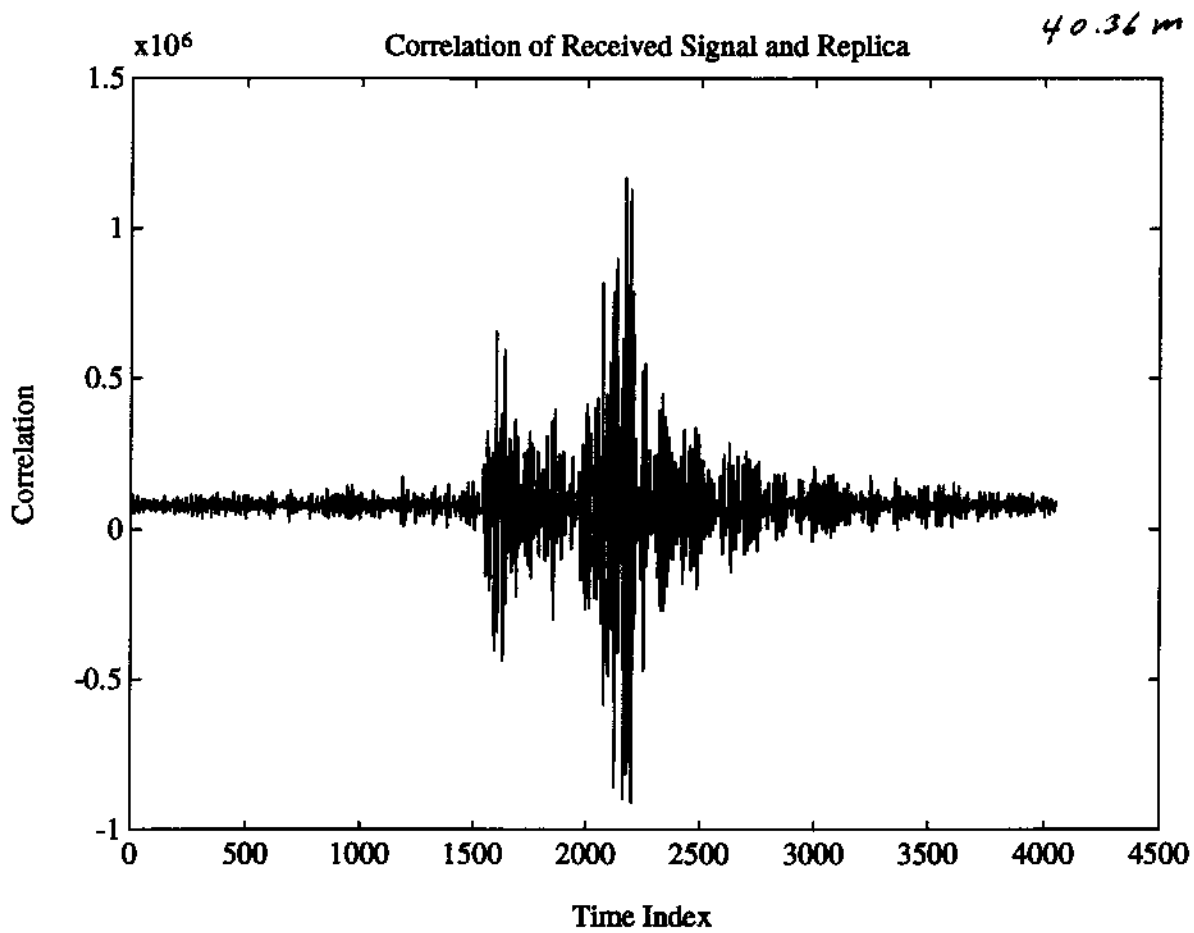






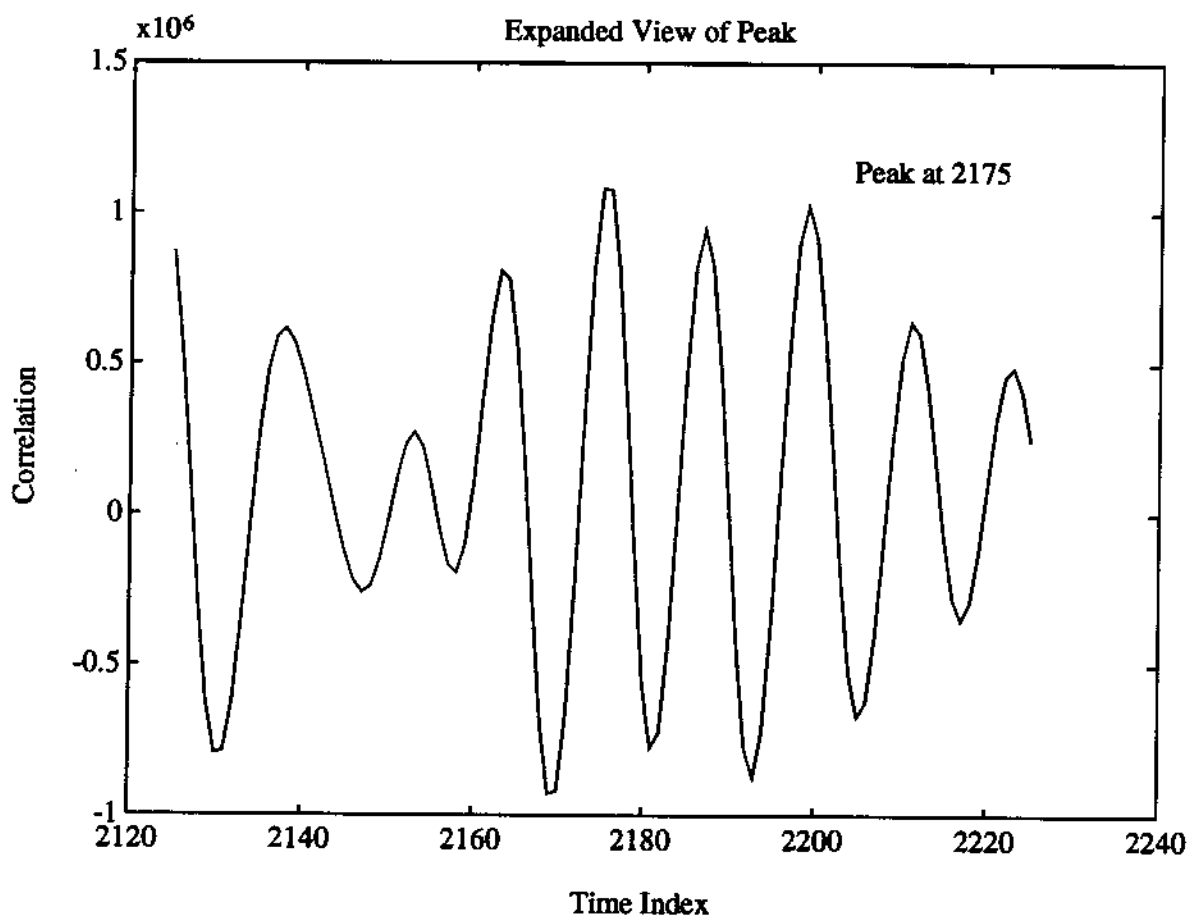
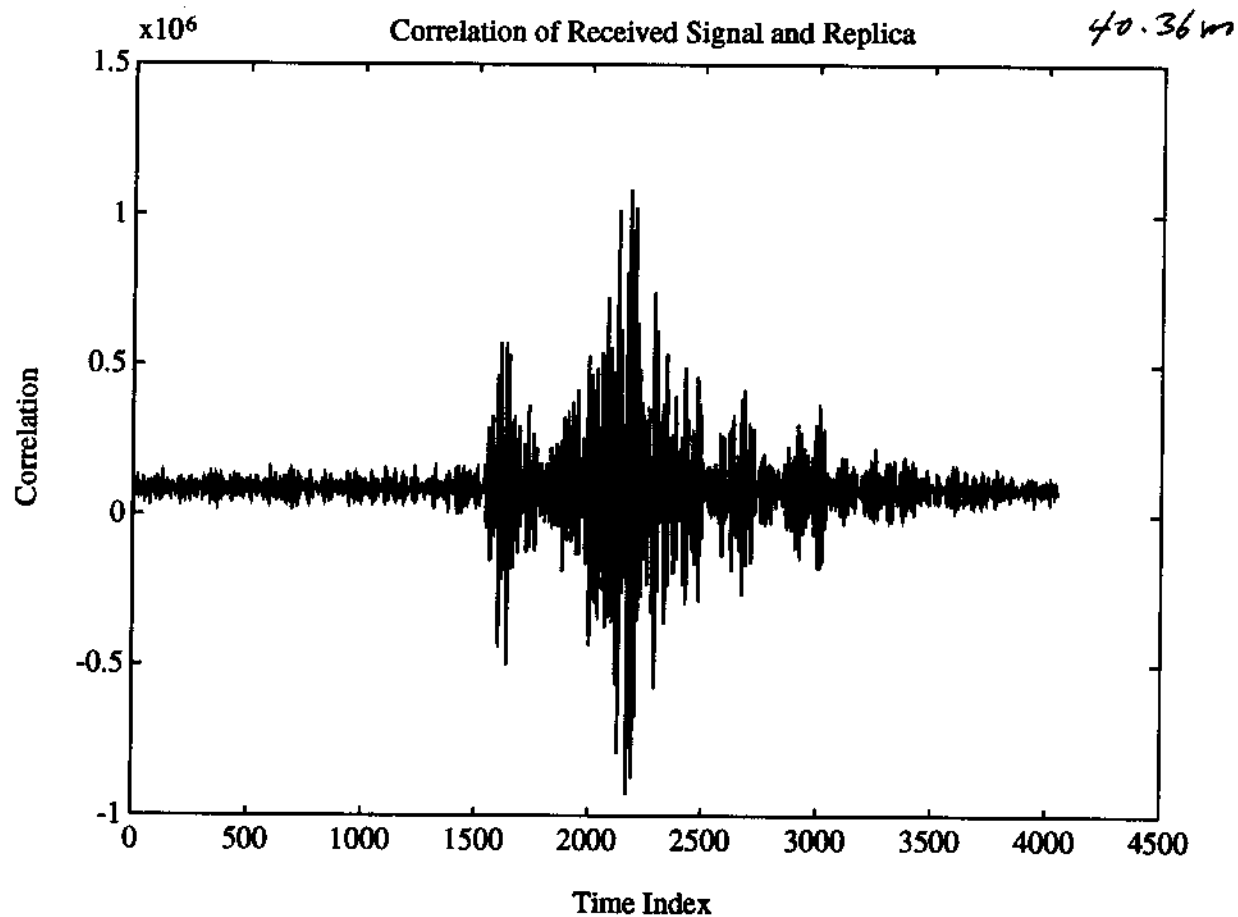


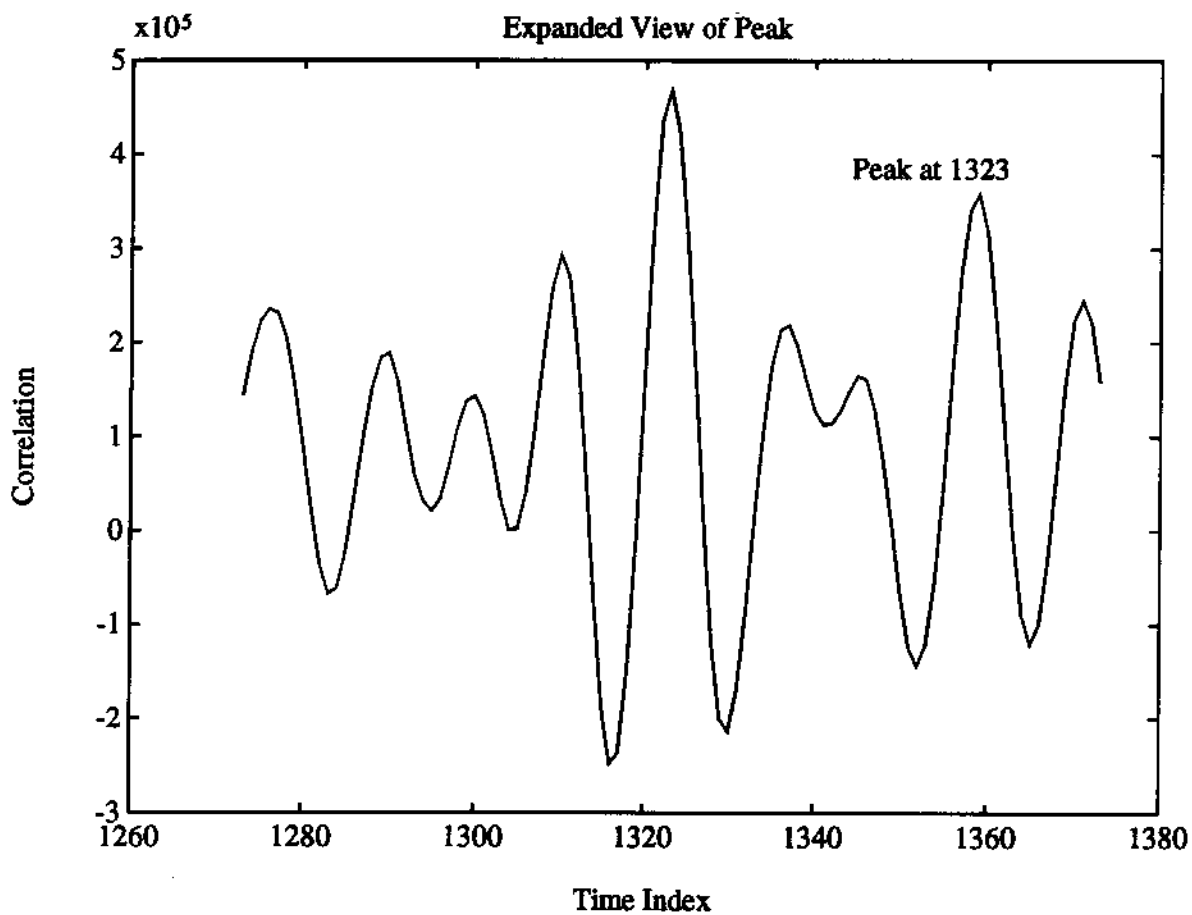
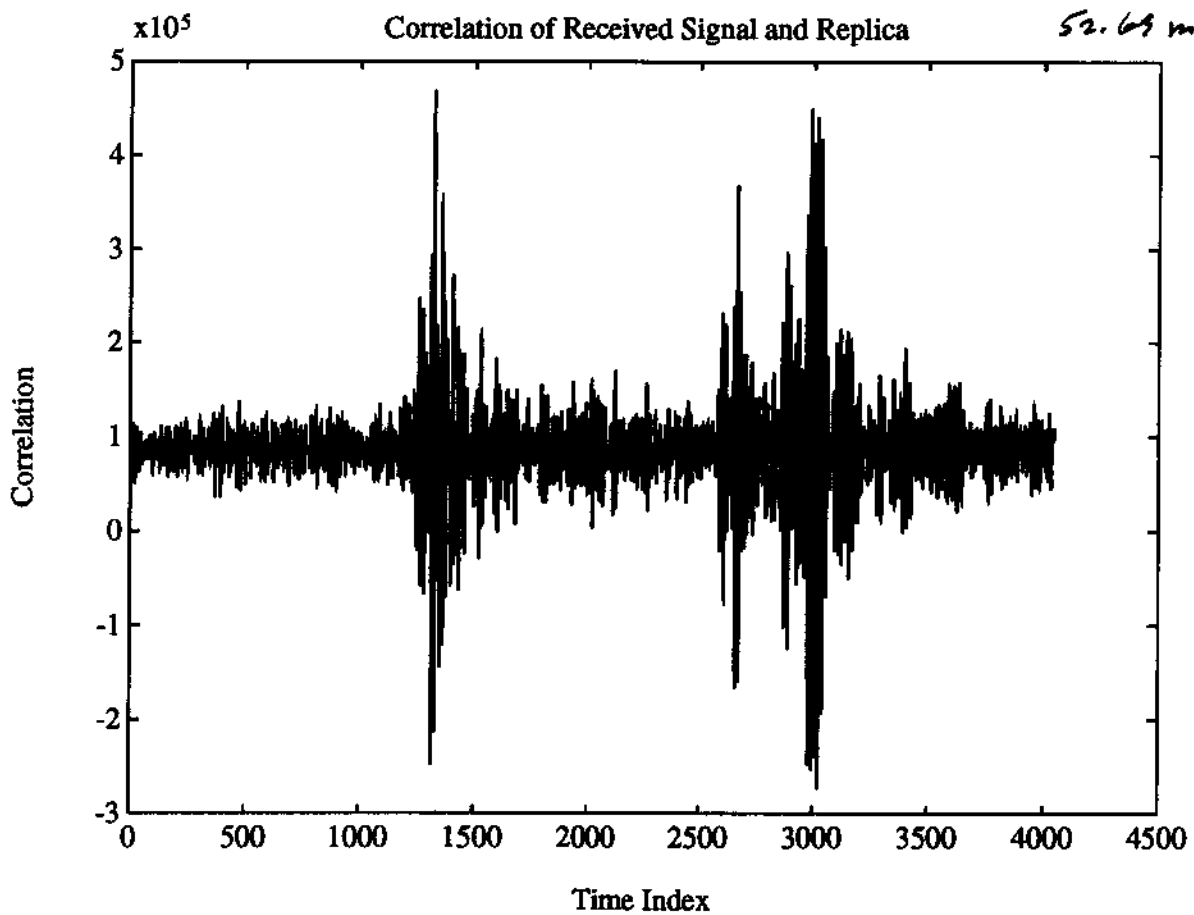




Signal 76
Rep 69

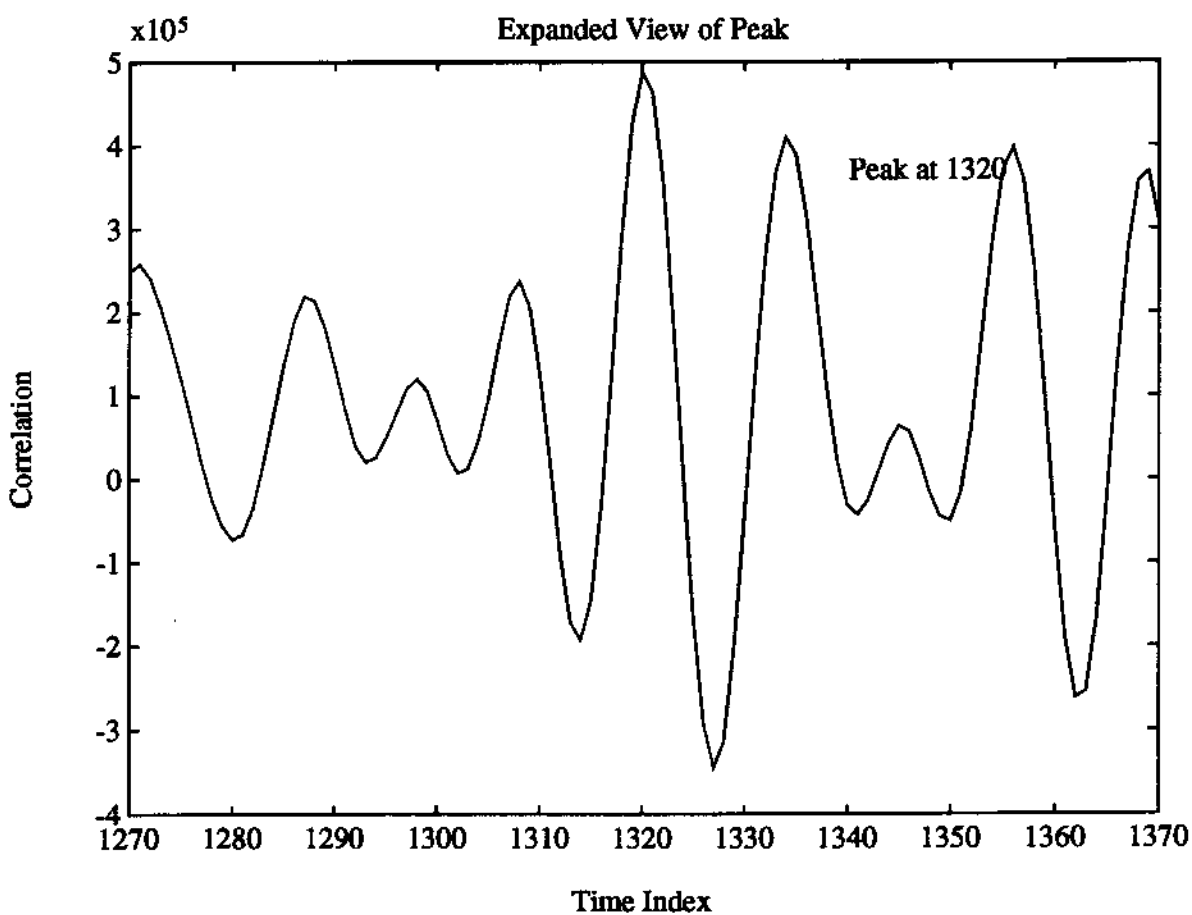
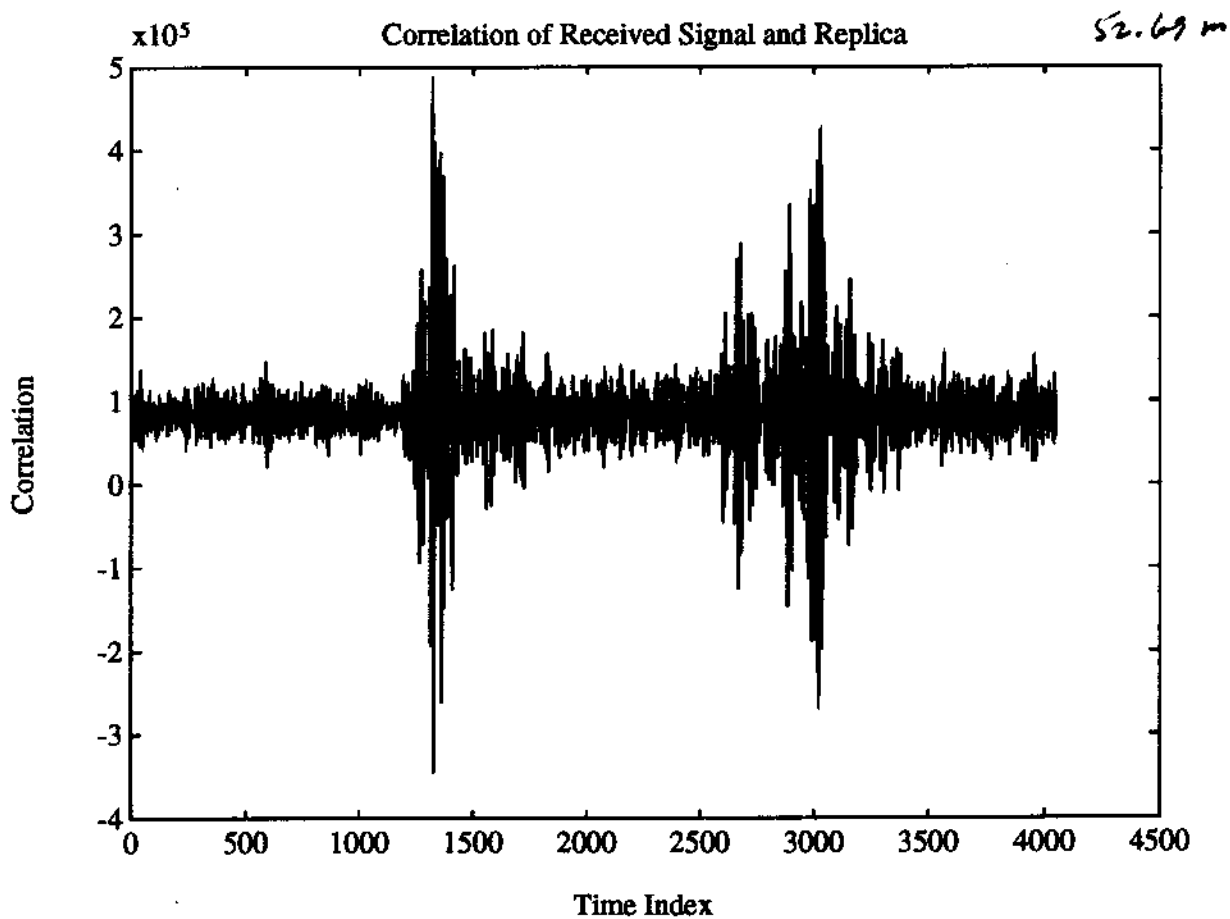
Offset 4000





Sig 78
Rep 69

offset 6000



Sig 79
Sep 69

Offset 6000